

Modelling light scattering by mineral dust using spheroids

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Modelling light scattering by mineral dust using spheroids: assessment of applicability

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Abstract

We study the applicability of spheroidal model particles for simulating the single scattering optical properties of mineral dust aerosols. To assess the range of validity of this model, calculations are compared to laboratory observations for five different dust samples at two wavelengths. We further investigate whether the best-fit shape distributions of spheroids for different samples have any similarities that would allow us to suggest a generic first-guess shape distribution for suspended mineral dust. We find that best-fit shape distributions vary considerably between samples and even between wavelengths, making definitive suggestions for a shape distribution difficult. The best-fit shape distribution also depends strongly on the refractive index assumed and the cost function adopted. However, a power-law shape distribution which favours those spheroids that depart most from the spherical shape is found to work well in most cases. To reproduce observed asymmetry parameters, best results are obtained with a power-law distribution with an exponent around three.

1 Introduction

The direct radiative impact of aerosols has been identified as one of the main sources of uncertainty in quantifying radiative forcing of the climate system (Forster et al., 2007). Mineral dust is one of the most widespread types of aerosol in the atmosphere with relatively high optical depth (Sokolik and Toon, 1996). In arid regions, rising concentrations of mineral dust due to desertification may even constitute the dominant anthropogenic mechanism for regional radiative forcing (Myhre and Stordal, 2001). The main sources of error in quantifying the optical properties associated radiative impact of mineral aerosols are the refractive index (Myhre and Stordal, 2001), the nonspherical morphology (e.g., Kahnert and Nousiainen, 2006; Kahnert et al., 2007) and, to a lesser extent, the size distribution (Myhre and Stordal, 2001). Accounting for aerosol morphology is also vital in remote sensing applications (e.g., Mishchenko et al., 2007).

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Both radiance and, even more so, polarisation can be strongly modulated by particle nonsphericity (e.g., Mishchenko et al., 1997; Schulz et al., 1998).

In climate studies, it is still common practice to model aerosol optical properties using the homogeneous sphere approximation (HSA). Spheroidal model particles have long been investigated as a first-order improvement of the HSA, (e.g., Mishchenko, 1993; Schulz et al., 1999). The idea behind this model is to introduce, in addition to the size parameter, one additional shape parameter while retaining a high degree of symmetry, thus keeping computational resource requirements manageable. Comparisons of model results and measurements indicate that spheroids are more versatile than other symmetric model particles, such as polyhedral prisms (Nousiainen et al., 2006). They have even proven superior to more advanced particle models that mimic the shape statistics of mineral dust samples (Veihelmann et al., 2006). In recent years, spheroids have been used operationally in remote sensing, such as in AERONET retrievals (e.g., Dubovik et al., 2006). Thanks to these recent successes, spheroids are likely to become established as an operational standard model for mineral dust.

However, there are three main issues that have, so far, not been adequately addressed. Validation studies have been confined to a fairly small selection of measurements. In Nousiainen et al. (2006), comparison of modelling results with measurements were limited to scattering experiments on feldspar aerosols at a wavelength of 632.8 nm. In Dubovik et al. (2006), this validation study was repeated and supplemented by observations made for the same feldspar sample at 441.6 nm. To increase our confidence in the spheroidal particle model, we need to perform a more comprehensive validation study, involving a larger selection of mineral dust samples with different size distributions and mineral compositions. Specifically, we need to identify the range of validity of the spheroidal particle model. For instance, recent findings suggest that spheroids may not be appropriate for modelling the optical properties of highly absorbing aerosols (Rother et al., 2006). Little is known about the validity of the spheroidal particle model at larger size parameters. Finally, to make use of the full flexibility of spheroids, models usually employ a shape distribution of spheroids, i.e., an

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ensemble of spheroids with different aspect ratios. In principle, each aspect ratio in the model can have a different weight, so we could introduce as many free parameters as we have different aspect ratios in our model ensemble. Both in remote sensing and, even more so, in climate modelling applications we need to reduce the number of free parameters by introducing reasonable a priori assumptions about the shape distribution of spheroids. This raises the difficult question: can we define a generic shape distribution that is likely to provide sufficiently accurate model results for a wide range of mineral aerosol compositions, size distributions, and wavelengths, and for different optical parameters.

Addressing these issues is pivotal for a wide range of applications within remote sensing and climate modelling. Here, we investigate these problems by performing a comprehensive validation study of the spheroidal particle model, assessing its range of validity, and studying the possibilities and limitations of generic shape distributions. In Sect. 2, we briefly review the theoretical background and in Sect. 3 we discuss the laboratory measurements employed in the comparisons. Results are presented and discussed in Secs. 4 and 5, respectively. Work is summarized in Sect. 6.

2 Methodology

We are primarily interested in modelling the elements of the Mueller matrix, which for randomly oriented particles has six independent elements (van de Hulst, 1957):

$$\mathbf{P}(\theta) = \begin{pmatrix} P_{11}(\theta) & P_{12}(\theta) & 0 & 0 \\ P_{12}(\theta) & P_{22}(\theta) & 0 & 0 \\ 0 & 0 & P_{33}(\theta) & P_{34}(\theta) \\ 0 & 0 & -P_{34}(\theta) & P_{44}(\theta) \end{pmatrix}. \quad (1)$$

Here θ denotes the scattering angle, i.e., the angle between the propagation directions of incident and scattered light. In the comparison with measurements, we consider the ratios P_{ij}/P_{11} for $\{i, j\} \neq \{1, 1\}$. The phase function P_{11} is normalised according to

$$\frac{1}{2} \int_0^\pi P_{11}(\theta) \sin\theta d\theta = 1. \quad (2)$$

The Mueller matrix elements are most relevant for the interpretation of remote sensing observations of radiance, polarisation, and depolarisation ratios. For climate applications, we also need to consider the asymmetry parameter g , which is the first Legendre moment of the phase function, i.e.,

$$g = \frac{1}{2} \int_0^\pi P_{11}(\theta) \cos\theta \sin\theta d\theta. \quad (3)$$

The asymmetry parameter is a measure for the partitioning between radiation scattered in the forward and backward hemispheres, which is important for quantifying the impact of aerosols on the radiative energy budget.

The size of the particles is often described relative to the wavelength λ of the light with a so-called size parameter x ,

$$x = \frac{2\pi r}{\lambda}, \quad (4)$$

where r is the radius of a volume-equivalent sphere.

The geometry of the spheroidal model particles is characterised by the aspect ratio $\epsilon = a/b$, where b denotes the dimension of the spheroid along the main rotational symmetry axis, and a denotes the corresponding dimension perpendicular to that axis. A prolate spheroid ($\epsilon < 1$) is obtained by rotating an ellipse about its major axis, while an oblate spheroid ($\epsilon > 1$) is constructed by rotating an ellipse about its minor axis.

For parametrising the shape distribution, i.e., a distribution of spheroidal aspect ratios, it is more convenient to use a shape parameter ξ (Kahnert et al., 2002a) rather than the aspect ratio ϵ . The shape parameter is defined as

$$\xi = \begin{cases} \epsilon - 1 & : \epsilon > 1 \text{ (oblate)} \\ 1 - 1/\epsilon & : \epsilon < 1 \text{ (prolate)} \\ 0 & : \epsilon = 1 \text{ (sphere)}. \end{cases} \quad (5)$$

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If we increase a for an oblate spheroid, then both ϵ and ξ will increase linearly with a . On the other hand, if we increase b for a prolate spheroid, then ϵ will decrease hyperbolically, while ξ will decrease linearly with b . The linear ξ -scale lends itself more easily for parametrising the shape distribution.

Previous attempts to fit modelled or measured reference Mueller matrices with a shape distribution of spheroidal model particles have consistently shown that spheroids with large values of $|\xi|$ contribute most to the best-fit ensemble (e.g., Kahnert, 2004; Nousiainen et al., 2006). For this reason, it has been suggested to parametrise the shape distribution according to a simple power law

$$p(\xi) \propto |\xi|^n, n \geq 0 \quad (6)$$

that gives the largest weight on those spheroids deviating most from the spherical shape. The power-law index n is an empirical parameter that has to be chosen such as to give the best agreement between modelling results and observations.

We make use of a database of pre-computed Mueller matrices for mineral dust particles (Dubovik et al., 2006). From the database, we can directly retrieve the scattering-matrix elements for any given aspect ratio averaged over a given size distribution. The results are compared to laboratory measurements of five different samples at two wavelengths, which are further discussed in Sect. 3. The refractive indices m of the samples are only known within a certain confidence range. For this reason, we perform computations for five different values of m with $\text{Re}(m) = 1.55$ and 1.7 , and $\text{Im}(m) = 0.001$ and 0.01 , as well as for an additional central value of $m = 1.6 + 0.003i$. Feldspar sample was additionally modeled with $m = 1.6 + 0.001i$, $m = 1.6 + 0.01i$, $m = 1.55 + 0.003i$ and $m = 1.7 + 0.003i$. The shapes include nine aspect ratios for oblate spheroids with $\epsilon = 1.2, 1.4, \dots, 2.8$, and nine aspect ratios for prolate spheroids with $\epsilon = 1/1.2, 1/1.4, \dots, 1/2.8$. This corresponds to shape parameters of $\xi = 0.2, 0.4, \dots, 1.8$ (oblate), and $\xi = -0.2, -0.4, \dots, -1.8$ (prolate). In addition, corresponding results for spheres are computed ($\epsilon = 1, \xi = 0$).

The size-averaged optical properties are calculated corresponding to each of the model shapes for all five samples at both wavelengths. Volume-equivalent size is

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assumed. The ensemble-averaged Mueller matrix is obtained averaging over the 19 aspect ratios weighted by the assumed shape distribution and also by their corresponding scattering cross-sections, which specify the total power scattered in all directions. Different shape distributions have been tested, with a focus on the $|\xi|^n$ model given in Eq. (6).

3 Measurements

We test our model by comparing the simulations with laboratory measurements of the Mueller matrices of different dust samples. The measurements are taken from the Amsterdam Light Scattering Database (Volten et al., 2006). An example of a measured Mueller matrix (with error bars) is shown in Fig. 1 along with example computations for varying spheroids with the corresponding size distribution. From the samples included in the database, we chose feldspar, red clay, green clay, loess, and Saharan dust. These samples have been measured by Volten et al. (2001) except for the green clay that was measured by Muñoz et al. (2001). The size distributions of the samples have been measured using a Fritsch laser particle sizer (Konert and Vandenberghe, 1997) and are also reported in the database. Although the samples have not been collected in the atmosphere, their shapes and compositions can be considered to be representative of atmospheric dust, and their sizes cover the expected size range. Presently, no measured Mueller matrices exist from samples collected from the atmosphere.

The properties of the samples are summarized in Table 1. The effective radii (r_{eff}) of the samples range from 1.0 μm to 8.2 μm and the effective standard deviations of radius (σ_{eff}) from 1.0 to 2.0. Following Hansen and Travis (1974), these quantities are defined as

$$r_{\text{eff}} = \frac{\int_r r \cdot \pi r^2 n(r) dr}{\int_r \pi r^2 n(r) dr}, \quad (7)$$

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$$\sigma_{\text{eff}} = \sqrt{\frac{\int_r (r - r_{\text{eff}})^2 \pi r^2 n(r) dr}{r_{\text{eff}}^2 \int_r \pi r^2 n(r) dr}}. \quad (8)$$

By replacing r by r_{eff} in Eq. (4), we can define the effective size parameter x_{eff} .

The samples have been measured at wavelengths of 441.6 nm and 632.8 nm, and cover scattering angles from 5° to 173° . Angles from 5° to 170° have been measured with 5° angular resolution, and angles larger than 170° with 1° resolution. The origins and the characteristics of the samples vary. For example, the shapes of the loess and Saharan dust are perhaps most representative of the atmospheric aerosols as they are collected from surface deposits. Feldspar sample, on the other hand, has been grinded from a feldspar rock and might thus be more angular than natural dust particles, but its size distribution resembles that of atmospheric dust in background conditions. The clay samples are commercial.

The measured Mueller matrices F are related to the phase matrix in Eq. (1) by an unknown normalisation coefficient: $P = \gamma \cdot F$. This means that the element ratios P_{ij}/P_{11} can be directly compared to the measured F_{ij}/F_{11} , but the phase function P_{11} first needs to be properly normalised according to Eq. (2). However, to compute the normalisation integral we need to have the phase function for the entire angular range from 0° to 180° . The phase function in the forward-scattering directions between angles from 0° to 5° are obtained directly from the corresponding computations. The simulated results are then matched with the observed phase function at the scattering angle $\theta = 5^\circ$. The backscattering angles, which do not contribute much to the normalisation integral, are extrapolated simply by using the measured value at 173° for all angles from 174° to 180° . Other methods for extrapolation have been suggested, e.g., by Liu et al. (2003), Kahnert and Nousiainen (2006), and Kahnert and Nousiainen (2007).

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4 Results

To compare simulations and measurements, we apply the measured size distribution, select a refractive index, and average the simulations over sizes and shapes as described in Sect. 2. The quality of fit is then evaluated by computing a cost function that quantifies the (dis)agreement between the simulations and measurements. As the preferred cost function, we use the area between the measured and modeled matrix elements (i.e., the well-known l_1 -norm; see, e.g., Kreyszig, 1993, page 994). The area is calculated only for scattering angles at which measurements are available, and it is normalised by dividing it with the angle span of the measurements ($\Delta\theta = 168^\circ$), and then expressed in percentages. We name this error-quantity ψ :

$$\psi = \frac{100\%}{\Delta\theta} \int_{5^\circ}^{173^\circ} |P_{\text{obs}} - P_{\text{sim}}| d\theta. \quad (9)$$

Here, $P = P_{ij}/P_{11}$, except that for the phase function $P = P_{11}$. The advantage here is that the errors of different scattering-matrix elements are readily comparable with each other. On the downside, the measurement uncertainty is not taken into account. If we want to give more emphasis for side scattering, we can use the $\log(P_{11})$ instead of P_{11} when calculating the ψ for the phase function. Indeed, we have mainly used the logarithmical form, as it gives more equal weight for all measurement angles.

We also experimented with many other cost functions, including χ^2 errors, Eq. (A7), summed over measurement points and the so-called δ_{80} value, which is defined such that at 80% of all observation points the discrepancy between measurements and simulations is smaller than δ_{80} . In the case of χ^2 and δ_{80} statistics, the cost function for assessing the agreement between measurements and model is calculated at the measurement points excluding 171° , 172° , and 173° to preserve angular equality in the analysis.

We note that we have restricted ourselves to using homogeneous, highly symmetrical model particles with smooth surfaces; real mineral particles are irregularly shaped, expected to be inhomogeneous and are likely to be composed of birefringent and thus

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anisotropic mineral species (e.g., Nousiainen, 2009). Moreover, we have assumed that the particle properties are not size or shape dependent while, for real atmospheric dust particles, this is not necessarily the case. For example, Claquin et al. (1999) propose different mineralogies for clay and silt fraction particles.

5 4.1 Assessing the overall performance of spheroids

We first want to establish how well the model of spheroids works for our samples. One way to do it would be to treat the shape distribution and the refractive index as free parameters and apply a fitting algorithm to find optimal values for these and then compute the cost function. However, since only positive weights are possible in the shape distribution, a non-linear fitting algorithm must be used, and such methods are not guaranteed to locate the global minimum even when multiple initial states are used. We thus adopt a simpler method where we investigate how well the measurement points are bracketed by simulations of individual spheroids based on any shape or composition considered. If a measurement point lies outside the range covered by the spheroids, then it is impossible to fit that measurement point with any choice of the shape distribution. This leads us to consider how well this necessary condition for successful fitting is met for different samples. The non-linear fits are only performed for selected cases and are considered in more detail in Sect. 4.2.

Investigations on how well the measured scattering-matrix elements can be covered by spheroids of different shapes and refractive indices are thus performed. The term “coverage” refers to the percentage of measurement points for which the measured values overlap with the range of values calculated for spheroids of different shapes. This gives an indication of how well the measurements can be modeled by using spheroids.

In Fig. 2 three scattering-matrix elements at $\lambda = 632.8$ nm have been plotted for each sample studied. Shown are both the measurement error bars and the coverages by different spheroids. The length of the error bar covered is accounted for each matrix element when calculating coverages, so that one single outlier point with a huge error bar might lower the coverage percentage significantly, which is exactly what happens with

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the feldspar F_{22} element in the upper right corner of Fig. 2. The coverages averaged over all matrix elements and for the P_{11} element separately are shown in Table 2 for both wavelengths. None of the measured samples are fully covered by the spheroids simulations. Feldspar stands out as the one sample that can most readily be modeled with spheroids for both wavelengths. Less than half of the measurement points for Saharan dust, on the other hand, are bracketed by the simulations, making this sample very challenging for the model of spheroids. It can be seen that, overall, the average coverage is better for samples with small r_{eff} . Likewise, the standard deviation is smaller for samples with small r_{eff} , indicating that coverages are also more consistent between different phase matrix elements for samples with small r_{eff} . Thus, the model of spheroids clearly seems more promising for samples with small r_{eff} . On the other hand, there does not seem to be systematic differences between the wavelengths, although the effective size parameter is over 40% larger at 441.6 nm than at 632.8 nm wavelength.

In Fig. 3, the minimum ψ values, Eq. (9), of all scattering-matrix elements for each sample are visualised as a function of the effective size parameter. A rising slope can be fitted on the data and its existence clearly indicates that the spheroid model works better for smaller sizes, especially in the case of the phase function. The slopes become slightly smaller if only the best-fit refractive indices for each element are considered. It is interesting to note that all the other scattering-matrix elements show strong dependence on size except for P_{12}/P_{11} and P_{34}/P_{11} , which are reproduced quite well with spheroids regardless of the size range.

4.2 Optimal shape distributions

Another, independent approach to assess the model of spheroids is to derive a shape distribution that provides the optimal fit to the measurements. This fit can be optimized separately for each sample, matrix element, and the refractive index. These optimized shape distributions can be found by using a nonlinear fitting algorithm based on the Levenberg-Marquardt method (for detailed description, see Appendix A).

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Optimizing the aspect-ratio weights separately for each matrix element is a time-consuming process and was, therefore, performed for a selected set only, including all the samples and matrix elements at $\lambda = 632.8$ nm with one refractive index ($m = 1.55 + 0.001i$) used for the scattering computations. In addition, fittings for the other wavelength ($\lambda = 441.6$ nm) and use of other refractive indices ($\text{Re}(m) = 1.55$ and 1.7 , $\text{Im}(m) = 0.001i$ and $0.01i$) were tested for feldspar and loess samples. These represent samples with small and large r_{eff} ; loess was chosen instead of Sahara due to its better coverage.

The fitting results (shown later in Fig. 7) reveal that in some cases, the optimal shape distribution of spheroids reproduce the measured scattering matrices quite well. As in the previous section, we once again see that the spheroids seem to work best for smaller size parameters: for feldspar, red clay, and green clay, the fits are relatively good; whereas, for loess and Saharan samples, the spheroids cannot produce scattering patterns similar to the measurements. Especially, the matrix elements P_{22}/P_{11} and P_{44}/P_{11} prove to be impossible to reproduce using spheroids. Figure 3 reproduced with the optimal shape distributions (not shown) leads to a $\psi - r_{\text{eff}}$ slope of 0.2 for the average of all elements as well as for that of P_{11} alone.

One main goal of this study is to investigate the validity of spheroidal model particles from a broader perspective. For this reason, we are particularly interested in general trends in the optimal shape distributions. The optimal aspect-ratio weights for matrix elements of all samples are collected in Fig. 4. There the wavelength is taken to be 632.8 nm and refractive index $m = 1.55 + 0.001i$. An immediate conclusion on the distribution is that extreme aspect ratios are clearly most common in the best-fit shape distributions. The form of the total distribution of weights encourages us to use a power-law shape distribution as an a priori assumption in more detailed studies of the search for the optimal value for n . Hence, a power-law function $C \cdot |\xi^n|$ is fitted in Fig. 4 (solid black line), resulting in $n = 18$. It is of interest to note that in a study by Nousiainen et al. (2006), the results favoured the extreme shapes, which in that study had $|\xi| = 1.6$. Here as well, the extreme shapes are found to be strongly favoured, but as now we

have $|\xi| = 1.8$ included, the $|\xi| \leq 1.6$ had far less weight on the results.

4.3 ξ^n parametrisation

Nousiainen et al. (2006) suggested a simple one-parameter (n) shape distribution for modelling mineral dust based on their simulations for the feldspar sample. Here, we investigate how well such a parametrisation works in general, and to what extent the best-fit n varies between the samples. To find the optimal n , we vary its value from 0 to 18 and identify the value that gives the smallest cost functions. At $n = 18$, the very extreme shapes ($\xi = -1.8$ and 1.8) include 88% of the scatterers and four most extreme shapes ($\xi = -1.8, -1.6, 1.6$ and 1.8) contain 99% of the population. The upper limit of $n = 18$ was chosen to include the best-fit value of 18 obtained in the previous section.

Table 3 summarizes the results for the optimal parametrized shape distributions under different criteria. As the cost functions, we consider eight different variations, namely:

- χ^2 for phase function P_{11} ;
- average χ^2 for the independent non-zero phase matrix elements, excluding P_{11} ;
- δ_{80} for P_{11} ;
- average δ_{80} for all independent non-zero phase matrix elements;
- the asymmetry parameter g ;
- ψ value for $\log(P_{11})$;
- average ψ for all matrix elements, each with m that produces the best fit;
- average ψ for all matrix elements with m that produces the best-fit g .

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Obviously, best fits are obtained at different n for different samples; this is natural and expected. Interestingly, with χ^2 criteria they are often obtained either with the least ($n = 0$) or the most ($n = 18$) extreme shape distributions considered. This is at least partly due to χ^2 approach giving huge emphasis to few points with very small measurement errors. The P_{11} element, often the most important for practical considerations, however, is uniformly best modeled with the equiprobable distribution ($n = 0$) or, when considering area differences (ψ), on average with $n = 0.4$. Curiously, unlike P_{11} , the best-fit n for the asymmetry parameter g is slightly larger. This may be because the calculation of the asymmetry parameter takes into account also the extrapolated diffraction peak whilst the other criteria only consider angles between 5° and 170° (or 173° for the two last columns in Table 3).

There seems to be a common trend that the phase function fits best when n is very small, whilst the fitting errors for polarisation components are minimized with values around $n = 10$ (which is when 70% of scatterers have $|\xi| = 1.8$ and 90% have $|\xi| \geq 1.6$) or even higher. This inconsistency indicates that the model of spheroids is not entirely accurate for real mineral dust particles.

The spheroids perform, however, much better than the HSA. This improvement in modelling accuracy is particularly clear for other samples except Sahara. The matrix elements that improve most are P_{12} , P_{22} and P_{33} ; ψ improvements are always at least 30% for the Sahara and 50% for the other samples. When the whole scattering matrix is considered, it is possible to reach 50% improvements on the average of all scattering matrix elements, excluding Saharan sample. In some special cases, individual scattering-matrix elements obtained from HSA may produce better fits, but the average ψ over all matrix elements is always at least 20% better for spheroids regardless of the n value or the refractive index (of those used here).

We experimented also with other kinds of shape distributions besides the ξ^n . The simplest correction, which slightly improved the results especially for small values of n , was to leave three or five of the most spherical shapes out altogether. Slight tuning of results could also be accomplished by shifting the distribution towards oblates or

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prolates. This approach usually made some scattering-matrix elements fit better whilst the others grew worse, rarely resulting in any significant overall improvement. Also a cosine shaped distribution was investigated, where the distribution peaked at the spherical shapes and decreased towards the more extreme axis ratios. This kind of distribution rarely matched the performance of an equiprobable distribution and was thus abandoned.

Modeled matrix elements produced by oblate particles vary from each other more than do models by prolates, which might be why shape distributions of solely oblate particles seem to produce slightly better fits to the measurements than those composed purely of prolates. A distribution that consists of both oblates and prolates usually performs best overall. It seems that both prolates and oblates are needed when good fits are sought throughout the scattering-matrix for the whole angle span. Occasionally, a shape distribution tweaked into either prolate or oblate side yielded slight improvements when compared to the simple ξ^n distribution. However, introducing an asymmetry between oblates and prolates would introduce an additional free parameter without consistent or even notable improvement to the results.

While the spheroid scheme is superior to spheres, its performance is far from perfect especially for samples with larger particles. The optimal shape distributions seem to vary from sample to sample but also, to some degree, between wavelengths. This implies that the optimal shape distribution for spheroids is not unambiguously connected to the actual shapes of the particles.

4.4 Robustness of model with respect to refractive index

The refractive index m of the samples is one of the sources of uncertainty in our analysis. Indeed, we do not even know to what degree the samples can be characterized with a single refractive index. To account for the uncertainty in m , simulations have been conducted with a variety of values, chosen to bracket the expected m range. Still, none of the values used is likely to be exactly right for any of the samples.

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One of the key questions related to this is whether the m dependence of scattering is sufficiently linear over the considered interval that, when we bracket the m values, we also bracket the single-scattering properties. In Nousiainen (2007), the dependence of the asymmetry parameter on the refractive index was studied for shape- and size distributions of spheroids. It was found that g depends on m monotonously and fairly linearly over a wide range of refractive indices. For individual, scattering-angle dependent phase matrix elements the situation is bound to be more complicated, but luckily the angular forms of the matrix elements do not seem to be overly sensitive to fairly modest variations in m (e.g., Nousiainen and Vermeulen, 2003; Muñoz et al., 2007). We are thus confident that, to a large extent, we also cover the single-scattering properties in our treatment.

That leaves us to consider how the results obtained depend on the refractive index. To this end, we take a closer look at the results for the nine different m for the feldspar sample and the five different m for the other samples. The summary of the results is given in Table 3. The first obvious observation is that the best-fit refractive index depends on the fitting criterion used. For example, for the feldspar sample for which the spheroid model works best, we obtain best-fit m from $1.55 + 0.001i$ to $1.7 + 0.01i$ at $\lambda = 441.6$ nm, from one extreme to the other, depending on the criterion adapted. The Saharan sample, on the other hand, favors the complementary extremes from $1.55 + 0.01i$ to $1.7 + 0.001i$. Behaviour is similar for $\lambda = 632.8$ nm. This result strongly implies that it is very challenging to reliably invert both the optimal shape distribution and the refractive index of real dust particles from the angular dependence of the scattering-matrix elements using simple model shapes such as spheroids. The best-fit m also depends on the wavelength and varies between samples, but these are expected and reasonable results.

To get more insight into the relation of the refractive index and shape distribution, we plotted cost functions bracketed over refractive indices for three samples (feldspar, red clay, and Saharan dust) in Fig. 5. The average ψ error, Eq. (9), of all matrix elements and the asymmetry parameter difference are shown for the wavelength of

441.6 nm for three different values of n (in columns). The longer wavelength behaves quite similarly and is not shown. Feldspar, whilst being clearly well mimicked with our model distributions, changes its 'best refractive index' behaviour with the changing shape distribution. On average, a combination of $m = 1.55 + 0.001i$ and $n = 3$ works best for it, although P_{11} can be best modeled with $m = 1.55 + 0.01i$. ψ values for P_{11} (not shown) and g of red clay (represented in fourth row of Fig. 5) are minimized with $m = 1.55 + 0.01i$ for all n . Green clay behaves similarly to the red clay and is not shown. The behaviour for total error is more varied. Perhaps surprisingly, Saharan dust is the only particle type that shows a very consistent refractive index behaviour for all n , averages and P_{11} (not shown) for both wavelengths. This might be partly due to poor performance of spheroids on the Saharan sample, as large errors may mask any subtleties caused by differing refractive indices. For loess, the $m = 1.7 + 0.001i$ provides the best fit on the average of all the elements and also on the P_{11} (not shown) element for the shorter wavelength. For 632.8 nm, the results of loess are not so conclusive as a lower real part and a higher imaginary part of the refractive index are also producing good modelling results for g . Overall, it seems that out of our options, reasonably good choices for refractive indices would be $m = 1.55 + 0.001i$ for feldspar, $m = 1.55 + 0.01i$ for both clays, and $m = 1.7 + 0.001i$ for both loess and Sahara.

Finally, we tested whether the matrices could be fitted better using a linear combination of different refractive indices rather than a single, fixed value. Thus, we assumed that the samples could be composed of multiple dust modes with their unique refractive indices; however, for simplicity, each mode was assumed to have the same shape and size distribution. More detailed considerations are outside the scope of this study. For comparison, we also calculated the refractive indices that produce the worst fits.

Curiously, none of the best or worst fits include the middlemost of our refractive index values, $m = 1.6 + 0.003i$. The reason for this is that our modeled scattering-matrix elements in most of the cases fall on one or the other side of the measurements, so that the most extreme modelling results will always be favoured with 100% concentration. This might indicate a problem with the overall suitability of the spheroid approach on

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real mineral dust. For example, if spheroids are incapable of producing sufficiently strong depolarisation or tend to under- or overestimate linear polarisation, it would be natural for the distribution to favour the m value that produces scattering matrices with the smallest error. The m -value thus retrieved might have little to do with the actual m value of the sample.

Alternatively, it could also be that the behaviour is connected to possible size distribution errors; it is well known that accurate measurements of size distribution are notoriously difficult (Reid et al., 2003). Then again, the size dependence of the phase matrix elements for shape-averaged spheroids is not strong. This can be seen very clearly from Fig. 9 of Nousiainen (2009), where the simulated phase matrices for the same samples as considered here are shown. In each case, the refractive index and the shape distribution has been the same, so the only differences between the samples are their different size distributions. As can be seen, the phase matrices are very similar. Therefore, errors in the size distributions are not expected to be critical for the results obtained here.

5 Generic shape distribution

Spheroidal model particles are a promising alternative to homogeneous spheres for both climate forcing and remote sensing applications. As a model geometry spheroids are significantly more flexible and provide, in most cases, more accurate results for the optical properties of mineral aerosols than homogeneous spheres. In the preceding sections we have investigated the versatility, but also the limitations, of the spheroidal particle model by performing a comprehensive validations study. In this section we focus on the question if we can give specific recommendations for a generic shape distribution of spheroidal particles that gives sufficiently accurate results for a wide range of mineral dust samples, spectral bands, and for different optical parameters. One challenge in using spheroidal model particles in operational applications, e.g. in a climate model, is that the shape distribution introduces many free parameters (as many

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as we have discrete aspect ratios in our ensemble of model particles). By specifying an a priori shape distribution, and by averaging the optical properties over this shape distribution, we reduce the free parameters to the particle size and refractive index, just like in the homogeneous sphere model. So replacing lookup tables based on spheres by those based on spheroids would be quite straightforward.

In satellite remote sensing, it may be possible to optimize the shape distribution to get best agreement with the measurements. However, it may be questioned how meaningful it is to perform fitting of optical observations with such a large set of free parameters. In climate models, on the other hand, such a fitting procedure is not even possible in principle. In the future, there might be source-dependent shape information available for climate modelling, but the authors are not aware of any such data being available currently. Further, as shown here, the connection between the real shapes and the best-fit shape distribution of spheroids may not be clear. Therefore, a generic shape distribution might be very usable for climate modelling purposes. For such a purpose, it is best to use a criterion that optimizes the asymmetry parameter, as g is a key parameter in computing radiative fluxes (e.g., Kahnert et al., 2005).

By taking the average of the shape distribution n values that minimize the error of the asymmetry parameter for the best performing refractive index for each particle and wavelength, we get $n = 2.9$. If only the clays and feldspar are taken into account, the distribution becomes slightly steeper: $n = 3.2$. The standard deviations between different samples, however, are notably large, namely 3 in both cases, meaning that quite likely the generic shape distribution is only able to portray different populations in average. Interestingly, the feldspar scattering matrix is, in average, best minimized with $n = 3.0$ for 441.6 nm and $n = 2.5$ for 632.8 nm.

In Fig. 6, ψ values obtained from the comparisons of simulations and measurements are illustrated. For each of the samples, we have used only one well performing refractive index, same for both wavelengths. For feldspar we used $m = 1.55 + 0.001i$, for red clay and green clay $m = 1.55 + 0.01i$, and for loess and Sahara $m = 1.7 + 0.001i$. Wider bars correspond to the wavelength of 632.8 nm, whilst the thinner black bars on

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top of them represent 441.6 nm. Each row corresponds to one sample from smallest (feldspar) to the largest effective radius (Sahara). Three different representations of the ξ^n distribution are shown for each scattering-matrix element, from lightest bars ($n = 0$) darkening towards $n = 3$ and $n = 10$ as indicated in the legend. The darkest rightmost bar represents ψ obtained when using HSA. Logarithmic area difference was also investigated in the case of P_{11} element, but it produced consistent results with the linear approach, so we left it out of the figure. It can be seen that, in almost all cases throughout the matrix elements, the ξ^n models work better than Mie solution (HSA) regardless of the n used. Only exceptions are seen in the P_{34} element of loess and Sahara sample, for which the Mie spheres perform slightly better than the equiprobable ($n = 0$) and $n = 3$ distributions, and in the Saharan samples P_{11} element at 441.6 nm, which is the only case when the Mie solution is the best option. This confirms that using any reasonable distribution of spheroids tends to produce better results than the Mie scheme. When the asymmetry parameter is the criterion, a reasonable first assumption for a spheroid shape distribution is to use the power law function with $n = 3$. For P_{11} element, the equiprobable distribution often works the best, whilst for the polarisation elements it might prove profitable to favour heavily the most extreme shapes ($n = 18$, which is the maximum used in our analysis).

When using a generic size distribution ($n = 3$ distribution) to describe the optical properties of any of our samples, the improvements compared to using HSA are generally huge. Only for the Saharan sample do the spheroids fail to decrease the error on asymmetry parameter from that produced by Mie particles. For the other particles, spheroids decrease the Mie error by 60–100%. (60% for green clay at 441.6 nm, 70% for red clay at 441.6 nm and more than 85% for both wavelengths of loess. Feldspar for both wavelengths and clays at 632.8 nm all have 100% improvement, meaning that the model successfully reproduces the measured asymmetry parameter).

Performance of spheroids is illustrated in Fig. 7, where three key scattering-matrix elements are shown for all samples. Measurements, spheroids with $n = 0, 3$ and 10, the homogeneous sphere approximation, and the optimal shape distribution results

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(Sect. 4.2) are plotted. It should be noted that the optimal distribution is acquired independently for all matrix elements, making the comparisons to the ξ^n model somewhat unfair. For all fitted shape distributions in the figure (green lines), the refractive index $m = 1.55 + 0.001i$ has been used. For the ξ^n models on the other hand we have always used an m that has been deemed best for the sample overall (see Sect. 4.4). This has led us to use $m = 1.55 + 0.001i$ only for feldspar, $m = 1.55 + 0.01i$ for both clays and $m = 1.7 + 0.001i$ for loess and Saharan samples. When comparing this figure with the values in Table 3, it is noted that the observed behaviour differs in some respects because of the used refractive indices. For example, while in Table 3 it can be seen that $m = 1.55 + 0.001i$ provides the smallest error for loess P_{11} with $n = 0$, the behaviour seen in Fig. 7 demonstrates how the choice of a higher real refractive index, here $m = 1.7 + 0.001i$, also leads to a preference of different, in this case of a larger n . Overall, it can be seen that the optimally tuned elementwise shape distributions do not lead into universally better results although locally the improvements might be notable.

6 Summary and conclusions

We started our investigation by identifying three open problems regarding the use of spheroidal model particles in remote sensing and climate modelling. We wanted to (i) perform a more comprehensive validation study to test the applicability of spheroids to modelling mineral dust optical properties; (ii) stake out the range of validity of the spheroidal particle model; and (iii) investigate if we can find a generic shape distribution of spheroids that is applicable to a broad range of mineral dust samples. To address these questions we have used shape distributions of spheroids to reproduce the scattering matrix elements measured in a laboratory for five different mineral dust samples at two wavelengths. We have made use of a database of pre-computed single-scattering properties for spheroids by Dubovik et al. (2006). The measured scattering matrix elements, as well as the size distributions and the estimated ranges for the

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complex refractive indices of the samples of interest, have been obtained from the Amsterdam Light Scattering Database (Volten et al., 2006).

Generally speaking, our results indicate that earlier validation studies that were limited to feldspar aerosols may have overestimated the versatility of spheroids for modelling mineral aerosol optical properties. This is especially true for mineral dust samples with larger effective size parameters. A clear trend is seen that the measurements of the smallest particles can most readily be reproduced whilst the scattering characteristics of largest particles are more difficult, often downright impossible, for spheroids to mimic. There are also differences in how the model fares on different scattering matrix elements. For example, a generally poor reproduction of P_{22} element with spheroids indicates strong limitations in predicting depolarisation properties of real dust particles.

We have also analysed the best-fit shape distributions for the samples at both wavelengths. We have used a non-linear fitting algorithm to find optimal shape distributions. The merit of this approach is to (i) obtain an upper bound for how faithfully the spheroidal particle model can fit the measurements; and (ii) try to find a general pattern in the best-fit shape distributions, which can help in the development of a generic shape distribution that could be used for atmospheric dust in cases when optimisation is not possible and no additional information about dust particles is available. The results indicate that shape distributions that put more weight on the most extreme aspect ratios often, but not always, provide the best fits of the measurements.

Based on this observation, we have investigated the performance of a simple one-parameter power-law shape distribution, Eq. (6). It is found that parameterisations with more free parameters do not lead to consistent improvements. Accordingly, the best-fit power-law shape distributions for different samples at different wavelengths have been compared. It turns out that it is impossible to suggest a single shape distribution that would be the best choice in all cases. Not only does the best-fit distribution vary between the samples, but it also varies between the wavelengths, the metrics used for specifying the goodness of fit, the quantities fitted, and the refractive index assumed. While it is rather reasonable that the best-fit distributions would be different for different

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5 samples that can consist of differently shaped dust particles, it is disconcerting that it also depends on the wavelength. This implies that the best-fit shape distributions do not necessarily correlate with the actual dust particle shapes. Indeed, these findings suggest that, when inverting dust physical properties from the single-scattering properties, the use of simplified model shapes may lead to erroneous results even when the agreement is good – the smallness of the residuals in the fitting may not guarantee the accuracy or correctness of the results.

10 Despite all shortcomings of the spheroidal particle model that this study revealed, our results confirm that spheroids are superior to the homogeneous sphere approximation (HSA) in almost all cases. Also, for climate modelling purposes, in which we mainly try to overcome the inaccuracy of the HSA, a shape distribution with $n = 3$ seems to be a reasonable choice. This distribution tends to produce significantly more accurate asymmetry parameter values than the HSA approach. We thus suggest a $n = 3$ distribution to be used in climate models. When one wishes to optimise the phase function, an equiprobable ($n = 0$) or very low value of n ($n < 1$) seems to perform better. When, on the other hand, one aims at the best all-around reproduction of the scattering-matrix, the optimal value of n often raises significantly; in half of our cases right up to our upper limit of $n = 18$. Also, the best-fit shape distributions obtained using the non-linear fitting algorithm resemble high- n shape distributions.

20 Recently, a database of single-scattering properties for tri-axial ellipsoidal mineral dust aerosols has emerged (Meng et al., 2010). Using tri-axial ellipsoids could possibly be the next logical step towards better operational aerosol modelling, although having all three principal axes differing from each other increases the complexity of the model. However, although most likely further enhancing the fits, these new model shapes do not necessarily bring any more reliability into retrievals, as their shapes are almost as distant from the real dust particle shapes as spheroids are. It is thus suggested that inversion algorithm developers used other criteria in addition to small residuals to validate the retrievals. There are also other promising shapes currently studied elsewhere, e.g., Poisson-Voronoi tessellation (Ishimoto et al., 2010) and nonsymmetric hexahedra

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(Bi et al., 2010), but single-scattering properties appear not be currently available for sufficient size- and wavelength range to consider climate model applications, for example.

Appendix A

Fitting of the Mueller matrix

Suppose we have a reference sample of particles with known optical properties. The Mueller matrix elements $P_{i,j}(\theta_k)$ have been measured at discrete angles $\theta_1, \dots, \theta_K$. The corresponding standard deviations of these measurements are denoted by $\sigma_{i,j,k}$. The scattering cross section C_{sca} can be obtained by determining the size-distribution and refractive index of the sample, and by performing Lorenz-Mie computations.

Suppose further that we have a set of model particles, such as spheroids of different shape parameters ξ_1, \dots, ξ_L with corresponding Mueller matrix elements $P_{i,j}^{\text{sim}}(\theta; \xi_l)$, and with scattering cross sections $C_{\text{sca}}^{\text{sim}}(\xi_l)$, $l = 1, \dots, L$. Given a shape-mixture with distribution function $\rho(\xi)$, the averaged optical properties of an ensemble of model particles are given by

$$\langle P_{i,j}^{\text{sim}}(\theta) \rangle = \frac{1}{\langle C_{\text{sca}}^{\text{sim}} \rangle} \int_0^\infty \rho(\xi) C_{\text{sca}}(\xi) P_{i,j}^{\text{sim}}(\theta; \xi) d\xi, \quad (\text{A1})$$

$$\langle C_{\text{sca}}^{\text{sim}} \rangle = \int_0^\infty \rho(\xi) C_{\text{sca}}(\xi) d\xi. \quad (\text{A2})$$

In discrete form this becomes

$$\langle P_{i,j}^{\text{sim}}(\theta) \rangle = \frac{1}{\langle C_{\text{sca}}^{\text{sim}} \rangle} \sum_{l=1}^L \rho_l C_{\text{sca}}(\xi_l) P_{i,j}^{\text{sim}}(\theta; \xi_l) w_l, \quad (\text{A3})$$

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$$\langle C_{\text{sca}}^{\text{sim}} \rangle = \sum_{l=1}^L \rho_l C_{\text{sca}}(\xi_l) w_l, \quad (\text{A4})$$

where the coefficients w_l denote the integration weights of the numerical integration method employed.

The objective is to optimise the shape distribution weights ρ_l such that the differential scattering behaviour of the ensemble of model particles mimics that of the reference sample as closely as possible. More specifically, we want to fit the quantity

$$B'_{i,j}(\theta; p_1, \dots, p_L) = \sum_{l=1}^L \rho_l C_{\text{sca}}(\xi_l) P_{i,j}^{\text{sim}}(\theta; \xi_l) w_l \quad (\text{A5})$$

to the quantity

$$A_{i,j}(\theta) = C_{\text{sca}} P_{i,j}(\theta) \quad (\text{A6})$$

by optimising the weights ρ_l , $l = 1, \dots, L$. Note that this approach is an extension of earlier work Kahnert et al. (2002b); Kahnert (2004); Nousiainen et al. (2006). The main difference is that we previously fitted the Muller matrix elements themselves, whereas in the present work we fit the Mueller matrix elements scaled by the scattering cross section. The former approach is equivalent to the latter only if the model particles and the reference system all have the same scattering cross section. Ideally, the measure employed for defining size-equivalence of nonspherical particles would ensure that nonspherical particles of equivalent sizes have the same scattering cross section. In practice, this is not always the case. For this reason, the approach employed in this study is slightly more accurate than that employed in our earlier work.

The linear least-squares method solves the fitting problem by minimising the quantity

$$\chi^2 = \sum_{k=1}^K \left(\frac{A_{i,j}(\theta_k) - B'_{i,j}(\theta_k; p_1, \dots, p_L)}{\sigma_{i,j,k}} \right)^2. \quad (\text{A7})$$

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A problem is that the weights p_1, \dots, p_L should have the properties of probabilities, i.e., they have to satisfy the constraints

$$\sum_{l=1}^L p_l w_l = 1 \quad (\text{A8})$$

$$0 \leq p_l \leq 1. \quad (\text{A9})$$

5 These constraints can be enforced by replacing the expression in Eq. (A5) by

$$B_{i,j}(\theta; h_1, 2, \dots, h_L, 2) = \frac{\sum_{l=1}^L h_l 2 C_{\text{sca}}(\xi_l) P_{i,j}^{\text{sim}}(\theta; \xi_l) w_l}{\sum_{m=1}^L h_m^2 w_m}. \quad (\text{A10})$$

The weights h_1, \dots, h_L are determined by minimising the quantity

$$\chi^2 = \sum_{k=1}^K \left(\frac{A_{i,j}(\theta_k) - B_{i,j}(\theta_k; h_1, 2, \dots, h_L, 2)}{\sigma_{i,j,k}} \right)^2. \quad (\text{A11})$$

Finally, one sets

$$10 \quad p_l = \frac{h_l 2}{\sum_{m=1}^L h_m^2 w_m}. \quad (\text{A12})$$

Equation (A12) ensures that the constraints given in Eqs. (A8) and (A9) are satisfied. Substitution of Eq. (A12) into Eq. (A10) yields an expression on the right hand side that is formally identical to that of Eq. (A5). However, in Eqs. (A10) and (A12) the coefficients p_l are forced to be non-negative and normalised to unity.

15 Finally the optimised weights p_l are substituted into Eqs. (A3) and (A4) to obtain the best-fit Mueller matrix and scattering cross section of the ensemble of model particles. Note that Eq. (A7) defines a linear least-squares problem. By contrast, Eq. (A11) needs to be solved with non-linear least-squares minimisation techniques. We employed a standard approach for such problems known as the Levenberg-Marquardt

method Press et al. (1992). Note further that the least-squares technique requires that the number of known quantities should be at least twice as large as the number of unknowns. Thus, the number of scattering angles, at which observations are available, should be at least twice as large as the number of model particles in the ensemble, i.e., $K \geq 2L$. In our case, $K=37$, and $L=17$, so the condition is satisfied.

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Table 1. Summary of the sample properties. The r_{eff} and σ_{eff} values have been computed from the measured size distribution; the $\text{Re}(m)$ is an estimate; $\text{Im}(m)$ is estimated to be between 10^{-2} and 10^{-5} for all samples.

	r_{eff} [μm]	σ_{eff}	$\text{Re}(m)$	main constituents	production	origin	colour
feldspar	1.0	1.0	1.5–1.6	K-feldspar, plagioclase, quartz	crushed	Finland	light pink
red clay	1.5	1.3	1.5–1.7	biotite, illite, quartz	commercial	France	red brown
green clay	1.55	1.2	1.5–1.7	illite, kaolinite, montmorillonite, quartz	commercial	France	green
loess	3.9	1.6	1.5–1.7	K-feldspar, illite, quartz, calcite, chlorite, albite	collected	Hungary	yellow brown
Saharan dust	8.2	2.0	1.5–1.7	quartz, clay minerals, calcium carbonate	collected	Saharan desert	yellow brown

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Table 2. Percentages of spheroid coverages for different samples.

%	441.6 nm			632.8 nm		
	F_{11}	avg.	σ	F_{11}	avg.	σ
feldspar	100	92	5	99	89	19
red clay	72	62	24	71	58	24
green clay	84	61	29	81	63	19
loess	76	55	35	74	59	27
Sahara	23	43	34	75	48	29

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Table 3. The best-fit n values of ξ^n shape distributions, Eq. (6), using different criteria. The refractive index with which the best-fit value was obtained is indicated by: $a = 1.55 + 0.001i$; $b = 1.55 + 0.01i$; $c = 1.7 + 0.001i$; $d = 1.7 + 0.01i$. and $e = 1.6 + 0.003i$. The last row shows the column averages when excluding the cases with $n = 18$.

	F_{11}	avg.	$\delta_{80} P_{11}$	$\delta_{80}(\text{avg.})$	g	$\psi \log(P_{11})$	ψ avg. best	ψ all Best-g
	441.6 nm							
feldspar	0.0 b	3.0 a	0 ab	0 ab	2.7 c	1.1 d	2.0 a	6.2
red clay	0.0 b	18 c	0 a	0 d	1.3 b	0.1 b	18 c	8.8
green clay	0.0 b	18 d	0 c	0 c	1.0 b	0.4 b	18 c	6.5
loess	0.0 d	18 c	0 a	0 d	4.4 c	0.4 c	18 c	11.0
Sahara	0.0 c	0.0 c	0 b	0 b	0.0 c	0.0 c	1.5 c	9.7
	632.8 nm							
feldspar	6.0 b	1.5 b	0 c	0 c	9.4 a	0.7 b	5.0 a	8.2
red clay	0.0 b	18 d	0 a	0 d	3.1 b	0.2 b	18 c	9.3
green clay	0.0 b	18 d	0 c	1 c	3.4 b	0.7 b	18 d	9.9
loess	0.0 a	0.0 a	0 b	0 b	5.7 e	0.1 a	18 c	7.0
Sahara	0.0 c	0.0 c	0 b	0 d	0.0 c	0.0 c	0.9 c	9.5
MEAN	0.6	9.45	0	0.2	3.1	0.4	11.7	8.8
w/o. 18		0.9					2.4	3.6

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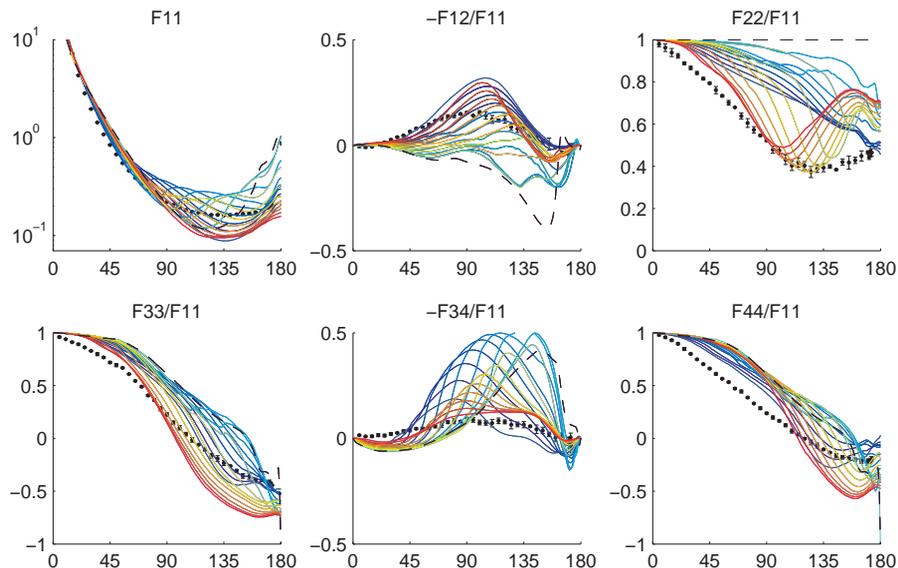


Fig. 1. Measured and simulated scattering-matrix elements for the loess sample at wavelength $\lambda = 632.8$ nm. The measurements are shown with small black dots and their error bars. Different solid lines depict scattering by different spheroids with refractive index of $m = 1.55 + 0.001i$, ranging from prolates (red) to oblates (blue). The dashed black line is the corresponding simulation for a sphere.

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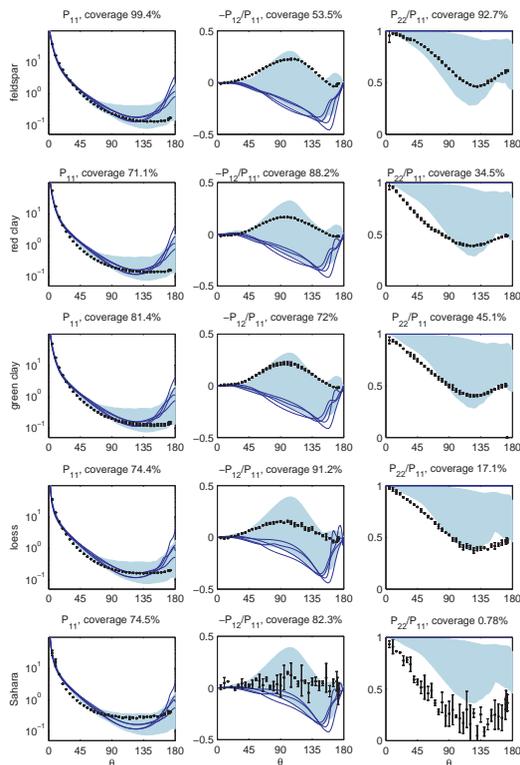


Fig. 2. Coverage of the measured scattering-matrix elements by model spheroids at 632.8 nm wavelength for the matrix elements P_{11} , $-P_{12}/P_{11}$ and P_{22}/P_{11} . Each row corresponds to one sample from smallest (feldspar) to the largest effective radius (Sahara). Measurements are shown with diamonds and error bars, and the shaded area indicates the coverage by different spheroids (all shapes and refractive indices), excluding spheres. The Mie spheres are shown with solid lines for each refractive index. To normalise the measured P_{11} element, it has been extrapolated with the $n = 3$ model shape distribution for the angles of 0° – 5° .

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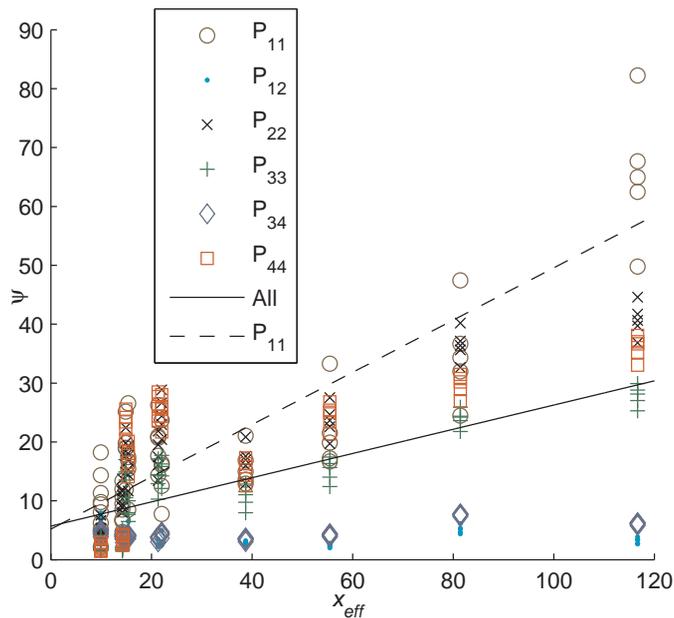


Fig. 3. Minimum ψ , Eq. (9), errors of the scattering-matrix elements as a function of the effective size parameter x_{eff} . All modeled refractive indices are included. The solid line (slope = 0.2) is linear regression representing the average of all dots while the dashed line (slope = 0.4) is solely for P_{11} .

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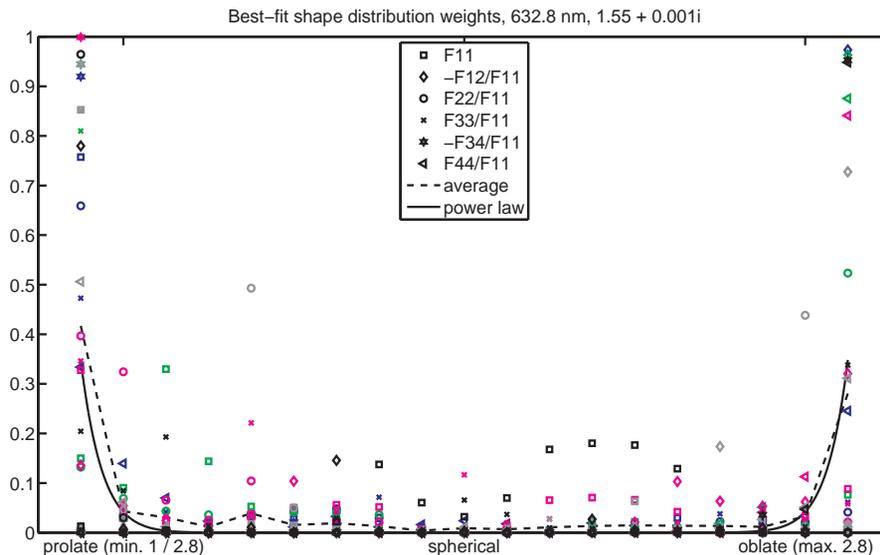


Fig. 4. Scatter plot of weights obtained for different spheroidal shapes when fitting different scattering-matrix elements of all samples considered. The colors refer to different samples: feldspar (blue), red clay (gray), green clay (green), loess (pink), and Saharan dust (black). Only the wavelength $\lambda = 632.8$ nm has been considered and m has been fixed at $1.55 + 0.001i$.

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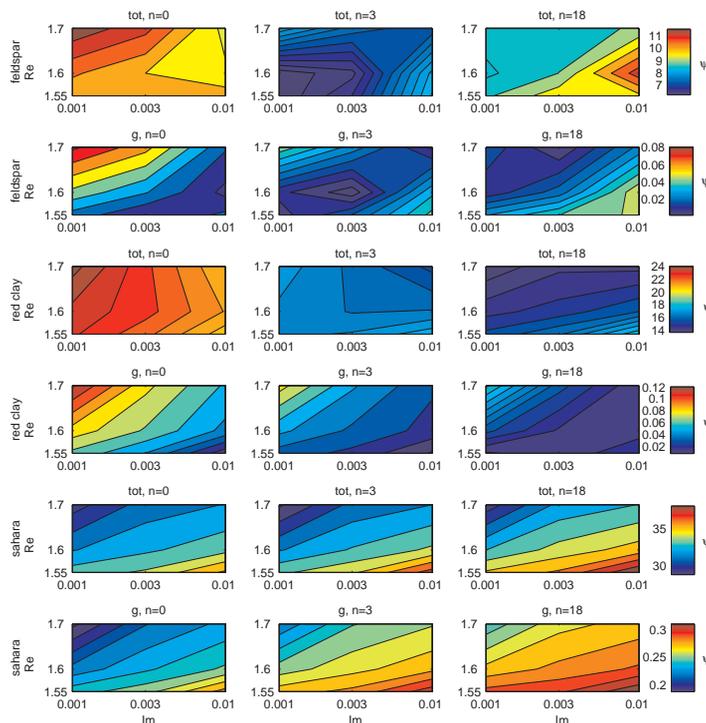


Fig. 5. Cost function dependence on the values of refractive index m . Columns from left to right represent different ξ^n distributions, Eq. (6), with $n = 0, 3$, and 18 , respectively. Small cost function values are shown in blue whilst the worst fit values are shown in red. One should note from the colorbars that the scale varies, values increasing with increasing particle size. Three minerals are represented with 441.6 nm, first two rows representing feldspar, then the red clay and last two rows Saharan dust. For each mineral two cost functions are shown on separate rows, namely the average ψ value, Eq. (9), of all scattering-matrix elements (tot.) and that of the asymmetry parameter error (g).

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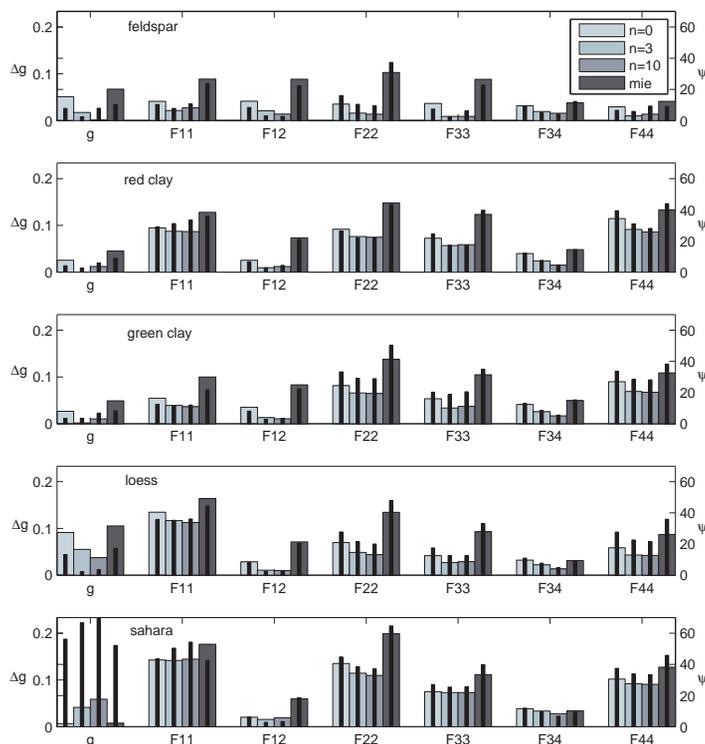


Fig. 6. ψ values, Eq. (9), for model scattering-matrix elements and asymmetry parameter error compared to the measurements. Wider bars correspond to the wavelength of 632.8 nm, whilst the thinner bars represent 441.6 nm. Each row corresponds to one sample from the smallest (feldspar) to the largest effective radii (Sahara). On each row there are seven bar groups. The left-most group and the left y-axis shows the asymmetry parameter error, whilst the other groups and the right y-axis are for different scattering-matrix element ψ values. In each group three different representations of the ξ^n distribution, Eq. (6), namely $n = 0, 3$ and 10 , are shown. The darkest rightmost bar represents the ψ value obtained when using Mie spheres.

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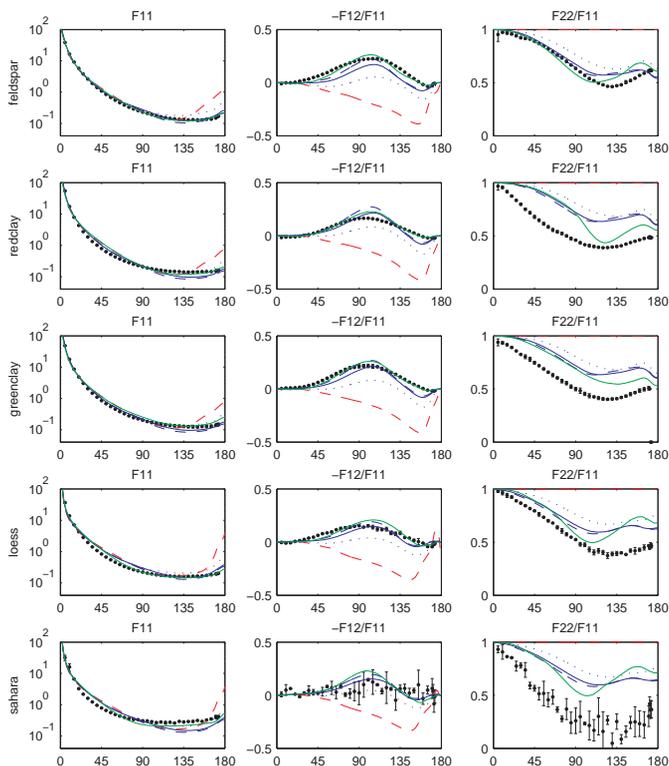


Fig. 7. Measurements with error bars (black), spheroid models (blue and green), and HSA (red) shown for the three key scattering-matrix elements of every sample. Three ξ^n model runs, $n = 0$ (dotted blue line), 3 (solid blue line), and 10 (dashed blue line) are shown as well as the optimal shape distribution (solid green line). Here we have used $\lambda = 632.8$ nm.

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