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Vertical profiles of droplet effective radius in shallow convective clouds

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Abstract

Vertical profiles of droplet effective radius (r_e) in shallow convective clouds are investigated using results from large-eddy simulations (LES) for clean (aerosol mixing ratio $N_a=25\text{ mg}^{-1}$), intermediate ($N_a=100\text{ mg}^{-1}$), and polluted ($N_a=2000\text{ mg}^{-1}$) conditions.

- Cloud-top r_e for cloud populations comprising clouds with different heights and at different stages of their development are used to construct a vertical profile of r_e . For the polluted and intermediate cases where precipitation is negligible, the constructed r_e profiles represent the in-cloud r_e profiles fairly well with a low bias (about 10%). For the clean, drizzling case the in-cloud r_e can be very large and highly variable and profiling based on cloud-top r_e is less useful. The differences in r_e profiles between clean and polluted conditions derived in this manner are however, distinct. The subadiabatic characteristics of the simulated cumulus clouds are investigated to reveal the effect of mixing on r_e and its evolution. Results indicate that as polluted and moderately polluted clouds develop into their decaying stage, the subadiabatic fraction f_{ad} becomes smaller, representing a higher degree of mixing, and r_e becomes smaller (~10%) and more variable. However, for the clean case, smaller f_{ad} corresponds to larger r_e (and larger r_e variability), reflecting the additional influence of droplet collision-coalescence and sedimentation on r_e . Profiles of the vertically inhomogeneous clouds as simulated from the LES and those of the vertically homogeneous clouds are used as input to a radiative transfer model to study the effect of cloud vertical inhomogeneity on shortwave radiative forcing. For clouds that have the same liquid water path (LWP), r_e of a vertically homogeneous cloud must be about 76–90% of the cloud-top r_e of the vertically inhomogeneous cloud in order for the two clouds to have the same shortwave radiative forcing.

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1 Introduction

Aerosol-cloud interactions are recognized as one of the largest uncertainties in the prediction of climate change. Representation of shallow convection in climate models is a major challenge because the relevant spatiotemporal scales are on the order of tens to hundreds of meters and seconds, i.e., scales much smaller than those that can be resolved by climate models, both now and in the foreseeable future (e.g., Lohmann and Feichter, 2005; Wang and Penner, 2009). Recent studies have shown that the manner in which warm clouds and their interaction with aerosol particles are represented by climate models has a marked effect on climate sensitivity – i.e., the Earth's temperature response to a doubling of CO₂.

The underlying processes associated with aerosol effects on clouds are qualitatively well-understood. Higher aerosol concentrations lead to an increase in cloud droplet concentration and a decrease in droplet size, thus an increase in cloud visible albedo for constant liquid water path (LWP) (Twomey, 1974, 1977). Higher aerosol concentration may also increase the amount of low-level cloudiness and cloud lifetime through a reduction of drizzle, imposing an additional cooling effect on the global climate system (Albrecht, 1989). However, the cloud lifetime effect and other processes such as the influence of aerosol on entrainment mixing are not well-understood (e.g., Jeffery and Reisner, 2006).

Quantification of aerosol-cloud interaction (ACI) is sometimes expressed as ACI = $-d\ln r_e/d\ln \tau$ at fixed LWP, where r_e is the cloud drop effective radius, and τ is the aerosol optical depth (Feingold et al., 2001; Feingold, 2003). McComiskey and Feingold (2008) found that an error of 0.05 in ACI can lead to large changes in the estimation of the radiative forcing. The fact that many field observations and satellite measurements to date have shown that ACI is highly variable (e.g., Feingold et al., 2003; Breon et al., 2002) suggests that there is large uncertainty in cloud albedo forcing. This is partly because physical mechanisms may vary under different conditions and locations, but ACI is also quite sensitive to the method of remote r_e retrieval (Rosenfeld and

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Feingold, 2003) and to the aerosol proxy for cloud condensation nuclei (McComiskey et al., 2009). In general, in-situ and ground-based observations of ACI tend to be higher and closer to the theory of droplet activation than those from satellites.

The horizontal and vertical variability of r_e imposes difficulty on r_e retrievals and hence uncertainty in ACI estimation. As shown in many field observations, droplet size not only exhibits horizontal heterogeneity, but also vertical stratification (e.g., Warner, 1955; Brenguier et al., 2000; Miles et al., 2000; Hudson and Yum, 2001; Twohy et al., 2005; Jiang et al., 2008; Lu et al., 2008; Arabas et al., 2009). The vertical stratification of droplet size must be resolved because it is central to both the cloud albedo and the precipitation process (Brenguier et al., 2003; Rosenfeld and Lensky, 1998). Although in situ measurements can resolve vertical profiles of droplet size, they cannot provide regional or global scale data sets for understanding and parameterization of aerosol effects on climate. Robust and widely applicable methods are needed for retrieving profiles of cloud droplet r_e . Ground-based remote sensing can retrieve droplet size profiles using millimeter cloud radar, with a constraint of microwave-derived LWP and assuming a droplet size distribution model, a fixed spectral breadth, and a constant droplet number concentration (Frisch et al., 1995). Measurements of r_e from satellite radiometers such as the Advanced Very High Resolution Radiometer (AVHRR) and Moderate Resolution Imaging Spectroradiometer (MODIS) tend to be confined to cloud top because a single near infrared (NIR) channel is more sensitive to the layer near cloud top rather than the lower layers (e.g., Nakajima and King, 1990). A recent study has revealed that the retrieval of droplet size can be strongly influenced by the vertical inhomogeneity of droplet size (Nakajima et al., 2010). Retrieving vertical profiles of r_e from satellite radiometers has only become feasible in recent years for low-level, non-precipitating stratiform clouds by assuming linear r_e profiles and with the use of MODIS shorter wavelength measurements that penetrate deeper into the clouds (Chang and Li, 2002; Chen et al., 2008).

To derive r_e profiles to study the potential for precipitation formation in convective clouds, Rosenfeld and Lensky (1998) and Lensky and Rosenfeld (2003) assumed that,

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in the absence of precipitation, satellite snapshots of cloud-top r_e of cloud fields consisting of individual clouds, each at different stages of their development can be used to construct an r_e profile from all clouds in the domain. In so doing, they assumed that cloud-top properties observed for clouds at different stages of their vertical growth are similar to the properties of a single cloud as it grows through various heights (Arakawa and Schubert, 1974). Because entrainment-mixing is significant for convective clouds, and because the top and the sides of convective clouds may experience different degrees of mixing (e.g., Warner, 1955; Blyth et al., 1988; Blyth, 1993; Burnet and Brenguier, 2007; Small and Chuang, 2008; Jiang et al., 2008; Lu et al., 2008), cloud droplet size at cloud top and inside of clouds may deviate from the adiabatic value to different degrees, and at different stages of the cloud lifecycle. However, if entrainment mixing is inhomogeneous, then cloud droplet size is probably not dependent on the degree of mixing (Freud et al., 2008). The assumption that cloud-top r_e acquired by satellites is representative of in-cloud r_e at the same height for convective clouds, as used in Rosenfeld and Lensky (1998), will be tested here.

In global climate model parameterizations, r_e is usually assumed to be vertically fixed or dependent on cloud thickness. Brenguier et al. (2003) pointed out that cloud vertical stratification must be taken into account in climate model parameterizations of cloud radiative properties and can be approximated with an adiabatic model for stratus clouds. It should also be noted that the stratified cloud model has been used to develop procedures for the retrieval of cloud geometrical thickness, liquid water content, and drop number concentration from the measurement of cloud radiances for stratiform clouds (Schüller et al., 2005). How to use this kind of cloud model for parameterization and retrieval in convective clouds remains uncertain because the mixing process can lead to significant changes in cloud microphysical properties (Warner, 1955).

In this paper, we use results from large-eddy simulations to investigate r_e vertical profiles in shallow convective clouds. It has been demonstrated that the sensitivity of cloud visible albedo to changes of cloud droplet size distribution is greatest for shallow clouds rather than very thick and water-rich clouds which have large visible albedos

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(Platnick and Twomey, 1994). The simulations in this study are based on the Barbados Oceanographic and Meteorology Experiment (BOMEX), during which steady-state cumulus convection was observed for a period of several days. More details of the simulations can be found in Xue and Feingold (2006). The spatial variability of r_e is investigated to shed light on implications for both satellite retrieval and model parameterization of the aerosol effects (Brenguier et al., 2003). We investigate whether r_e profiles can be constructed using r_e information at cloud top from satellite measurements for convective clouds. The in-cloud variability of r_e in each case is compared to the variability due to aerosol effects. The evolution of r_e profiles and the degree to which r_e profiles are affected by mixing are also studied. A plane-parallel radiative transfer model is then used to investigate the effect of cloud vertical inhomogeneity on shortwave radiative forcing. The model data and methods are described in Sect. 2. Results and discussions are presented in Sect. 3, and conclusions are summarized in Sect. 4.

15 2 Data and method

Data used in this study are model output from a set of large-eddy simulations of trade cumuli with aerosol mixing ratios of $N_a=25$, 100 and 2000 mg^{-1} (mixing ratio units of mg^{-1} are approximately equal to cm^{-3}) that represent clean, intermediate, and polluted conditions, respectively. Details of the LES model and the case are given in Xue and Feingold (2006). Precipitation is light in the clean case and negligible in the intermediate and polluted cases. We choose different aerosol concentrations to see if the r_e profiles have different characteristics under non-precipitating and drizzling conditions. r_e is calculated based on the droplet size distribution that is represented by 33 bins from $1\text{--}2500\text{ }\mu\text{m}$ radius. The large-eddy simulations were performed in a doubly periodic, $6.4\text{ km}\times 6.4\text{ km}\times 3\text{ km}$ domain. The model grid-spacing is $\Delta x=\Delta y=100\text{ m}$, and $\Delta z=40\text{ m}$. All the simulations were run for six hours, but analysis was only performed over the last four hours. Model output was sampled every 5 min, thus 48 snapshots in the last four hours of simulation in each case were analyzed.

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The areas where $LWP > 10 \text{ g m}^{-2}$ are considered as cloudy areas. We define cloud-top r_e in each cloudy column as the r_e at the highest grid point that has liquid water mixing ratio $q_l > 0.01 \text{ g kg}^{-1}$. Cloud-top r_e is used to construct a profile of r_e and compared to the r_e profile from all cloud samples for each case. The purpose is to test if the constructed r_e profiles can represent the in-cloud r_e profiles. Because cloud-top droplet size is usually affected by entrainment mixing, we also add two additional measures of cloud-top r_e to the analyses: One is the r_e at one grid below the highest grid point that has $q_l > 0.01 \text{ g kg}^{-1}$; the other is the maximum r_e in the column (usually several grid points below the highest grid point that has $q_l > 0.01 \text{ g kg}^{-1}$). Results using different definitions of cloud-top r_e will be discussed in Sect. 3.

The plane-parallel radiative transfer model SBDART (Santa Barbara DISTORT Atmospheric Radiative Transfer; Ricchiazzi et al., 1998) is used to investigate the shortwave radiative forcing of shallow cumulus clouds. The focus is on the effect of cloud vertical inhomogeneity, and so we ignore three-dimensional radiative effects, which were addressed by Zuidema et al. (2008). Because the simulated cumulus clouds cover heights between $z=600 \text{ m}$ and $z=2200 \text{ m}$, but most clouds have cloud tops lower than $z=1600 \text{ m}$, we use a solid cloud layer covering the height of $z=600\text{--}1600 \text{ m}$ in the SBDART model. The vertical inhomogeneity of the solid cloud layer is represented by 5 sublayers, each of which has a depth of 200 m. The liquid water content (LWC) and r_e of each sublayer is an average of the large-eddy simulation results in that layer for each of the simulated cases. We compare the shortwave radiative forcing of the vertically inhomogeneous clouds with that of the vertically homogeneous clouds that have the same LWP. The SBDART model also requires setup of the atmospheric profile, aerosols, surface model, and so on. We select the tropical atmospheric profile, which is one of the six standard atmospheric profiles in the model. The aerosol optical depth in the cloud-free atmosphere is simply set to zero because we only investigate the difference of radiative forcings from a vertically homogeneous cloud and a vertically inhomogeneous cloud. The surface model in SBDART is selected as ocean water. Solar zenith angle is varied from 0–90 degrees and only results for the 60 degree are shown

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3 Results

3.1 r_e profiles of cloud population

Figure 1 shows r_e profiles of the cloud population over the last 4 h of simulation. The r_e profiles from all cloud samples in each case are shown in Fig. 1a–c, and the 50th percentile of the r_e is shown as a reference (black lines). In the polluted and intermediate cases where precipitation is suppressed, r_e increases with height and also exhibits variability at each level (Fig. 1a, b). In the clean case where precipitation develops, r_e generally increases with height but with significantly higher variability at all levels (Fig. 1c). The r_e profile is complicated in the clean case due to droplet collision-coalescence and sedimentation. Note that for clarity the drizzle-mode drops larger than 50 μm radius (both inside of the clouds and below the cloud base) in the clean case are not shown (the scale of the x -axis is set to 50 μm).

The constructed r_e profiles using cloud-top r_e are shown in Fig. 1d–f. The 50th percentile of the r_e from all cloud samples is also shown as a reference (black lines). The constructed r_e profiles have similar properties to the r_e profiles from all cloud samples, although with a low bias (as can be seen from the median r_e in the constructed r_e profile compared to the 50th percentile of r_e from all cloud samples in each case). This bias is about 0.5 μm ($\sim 10\%$) in the polluted case, 1 μm ($\sim 10\%$) in the intermediate case, and 2 μm ($\sim 10\%$) in the clean case. The constructed r_e does represent the in-cloud r_e in the polluted and intermediate cases fairly well, with a low bias ($\sim 10\%$), providing evidence that the cloud-top r_e from satellite measurements can generally be used for profiling r_e . For precipitating clouds, the significant variability suggests that cloud-top r_e from satellite measurements may be unreliable.

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As expected, both the r_e profiles from all cloud samples and the constructed r_e profiles in Fig. 1 indicate that r_e becomes larger when aerosol mixing ratio changes from 2000 mg^{-1} , to 100 mg^{-1} , and to 25 mg^{-1} (Twomey, 1974). Results indicate that r_e variability in the polluted and intermediate cases is relatively small compared to the aerosol effects on r_e . Although r_e variability in the clean case is large, the three cases still show distinct differences in r_e for the relatively large range in aerosol conditions considered here. Successfully distinguishing the differences in r_e between clean and polluted air masses using satellite retrievals or other measurements will depend on the existing aerosol gradient and the accuracy of the remote r_e retrieval.

Figure 2 shows the constructed r_e profiles using different measures of cloud-top r_e . Results using the r_e at one grid point below the highest grid that has $q_l > 0.01 \text{ g kg}^{-1}$ are shown in Fig. 2a–c. The constructed r_e profiles closely represent the in-cloud r_e , especially in the polluted and intermediate cases. Figure 2d–f presents constructed r_e profiles with the maximum r_e in each column. The r_e profiles constructed in this way have a high bias ($\sim 5\%$) compared to the in-cloud r_e . Therefore, the constructed r_e profiles show progressively larger r_e when using the following measures of cloud-top r_e : (1) r_e at the highest grid point with $q_l > 0.01 \text{ g kg}^{-1}$; (2) r_e at one grid point below the highest grid with $q_l > 0.01 \text{ g kg}^{-1}$; and (3) the maximum r_e in the column. This may be due to the entrainment mixing at cloud top, as discussed in more detail in Sect. 3.3. But similar to results in Fig. 1, the constructed r_e profiles using different measures of cloud-top r_e still show the aerosol effects on r_e and the distinction between clean, intermediate, and polluted conditions.

3.2 Evolution of r_e profiles of individual clouds

Figure 3 shows the evolution of r_e profiles of individual clouds at different stages of their lifetime in the simulated cases. We focus on individual clouds that are bigger but do not merge with other clouds or break up into smaller ones throughout their lifetime. Only three r_e profiles during the development of each cloud are shown here. The r_e

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profiles of an individual cloud evolving for 40 min in the polluted case are shown in Fig. 3a. The cloud starts to grow from 3 h 15 m, increases to the maximum height at 3 h 35 m, and completely dissipates after 3 h 55 m. It is interesting that the cloud-top r_e is smaller at 3 h 25 min (growing) and 3 h 45 min (decaying) compared to the r_e at the same heights at 3 h 35 min (growing and reaching the maximum height). The r_e profile at 3 h 35 min seems to fill in the cloud-top r_e of the lower clouds. In addition, the decaying cloud (3 h 45 min) has slightly smaller r_e than the growing cloud reaching the maximum height (3 h 35 min). These characteristics of r_e profiles during cloud development may be explained by a combination of the effects of preconditioning and mixing on r_e , as discussed in detail in Sect. 3.3.

Figure 3b shows a cloud in the intermediate case that starts to grow from 4 h 10 min and completely dissipates after 4 h 35 min. It grows to its maximum height at 4 h 30 min. Similarly, the r_e at 4 h 30 min seems to fill in the cloud-top r_e of the lower clouds at the other two times. The r_e of the decaying cloud (4 h 35 min) is also slightly smaller than those of the growing clouds (4 h 20 min and 4 h 30 min).

The evolution of a cloud in the clean case is more complicated (Fig. 3c). The cloud evolves from 2 h 30 min to 3 h 5 min. At 2 h 50 min, large drops form due to collision-coalescence. We can clearly see the condensation regime at a height of 0.7–1.2 km near cloud base where droplet growth is relatively slow, and the coalescence regime at the height of 1.2–1.8 km where the growth is much faster (Rosenfeld and Lensky, 1998). This confirms the findings in Figs. 1 and 2 that, for clouds that are precipitating, it is difficult to use the cloud-top r_e to infer the in-cloud r_e .

3.3 Difference of r_e profiles in growing and decaying clouds

The cloud population over the last 4 h of simulation in each case is divided into growing clouds and decaying clouds based on a criterion of maximum vertical velocity. A cloud is considered as a growing (decaying) cloud if its maximum vertical velocity is higher (lower) than 2 m s^{-1} . Ideally a cloud that has a maximum vertical velocity smaller than 0 m s^{-1} might be considered as a decaying cloud. However, we note that using the

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0 m s⁻¹ criterion leads to very few samples for decaying clouds, and that using the 1 m s⁻¹, and 2 m s⁻¹ criteria provides progressively more samples for the decaying clouds. The difference of r_e profiles in the growing and decaying clouds is very similar when using these three criteria. Figure 4 shows the r_e profiles in growing and decaying clouds using the criterion of a 2 m s⁻¹ maximum vertical velocity. The 50th percentile of r_e from all cloud samples in each case is also shown as a reference (black lines). It is seen that, for the non-precipitating polluted and intermediate cases, r_e is generally smaller in the decaying clouds than in the growing clouds, probably because of progressively stronger entrainment mixing, as will be discussed next. In the polluted case, r_e in the decaying stage is about 0.5 μm smaller than that in the growing clouds in general. Similarly, in the intermediate case, r_e in the decaying clouds is about 1 μm smaller than that in the growing clouds. The clean case has large drops in both the growing and decaying stages because large drops form due to collision-coalescence as clouds develop into mature and decaying stages.

Because the above results show that cloud-top r_e is slightly smaller than the in-cloud r_e (Fig. 1), and that r_e in a decaying cloud is smaller than that in a growing cloud (Figs. 3 and 4), we now investigate the effects of entrainment mixing on r_e and its evolution. We use the adiabatic fraction f_{ad} , defined as the ratio between the simulated cloud water to the adiabatic value (e.g., Pawlowska et al., 2006), to represent the subadiabatic characteristics of clouds. Note that our LES model uses time-splitting between dynamical and microphysical processes and therefore implicitly assumes the homogeneous mixing process. Our investigation here would represent a situation where r_e of convective clouds may be affected by mixing to the maximum extent (extremely homogeneous mixing). On the other hand, for adiabatic clouds or an extremely inhomogeneous mixing situation, cloud-top r_e should be the same as the in-cloud r_e at the same height. As for a cloud that experiences both homogeneous and inhomogeneous mixing processes (Lehmann et al., 2009), the effect of mixing on r_e should be between the extreme situations discussed above. Whether cumulus clouds experience homogeneous mixing or inhomogeneous mixing is not the focus of this study. However, a previous study

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has shown that assuming extreme inhomogeneous rather than homogeneous mixing results in a small (2–5%) reduction in cloud-averaged droplet number concentration and a commensurately small increase in r_e for marine stratocumulus clouds (Hill et al., 2008).

Figure 5 shows vertical profiles of f_{ad} in the three simulated cases. It is seen that f_{ad} is significantly smaller than 1. In the lower layer of the clouds (from cloud base to about 0.8 km), f_{ad} increases with height. Above this layer, f_{ad} generally decreases with height to about 1.6 km. Because the cloud population is dominated by clouds that are several hundred meters deep in the simulated cases, the fact that f_{ad} decreases from 0.8 to 1.6 km indicates that liquid water mixing ratio in cloud samples near cloud top is reduced by entrainment, as revealed in observations (e.g., Warner, 1955; Blyth et al., 1988; Blyth, 1993; Miles et al., 2000; Small and Chuang, 2008). The characteristics of the bigger clouds are averaged out by the smaller clouds in this layer. From 1.6 km to about 2 km, the increased f_{ad} at cloud top in each case is due to the few bigger and deeper clouds that have higher f_{ad} . It is also likely that these larger clouds are growing in preconditioned, moistened air and that drops in this region are less prone to evaporation. Notice that for the polluted and intermediate cases where precipitation is negligible, f_{ad} generally represents the degree of mixing. But in the clean case where precipitation develops, deviation from adiabatic liquid water content is not only affected by mixing, but also by drop sedimentation. The removal of liquid water by sedimentation is probably the reason that f_{ad} is relatively low in the clean case compared to the other two cases.

As a cloud develops, the mixing process may become different and f_{ad} may change (Lehmann et al., 2009). Figure 6 shows the f_{ad} evolution of the individual clouds discussed in Fig. 3. It is seen that f_{ad} generally decreases, representing stronger entrainment mixing, as the individual clouds grow and dissipate. The enhanced degree of mixing during cloud development can cause a slight decrease in r_e , as can be seen in Fig. 3. It should be noted that the decrease in f_{ad} is not monotonic, and shows evidence of pulsating growth as discussed in Heus et al. (2009). Although the LES model output

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in this study is sampled only every 5 min, which is similar to the time scale of pulses, the non-monotonic evolution of f_{ad} is consistent with the concept that a cloud can be seen as a sequence of pulses (French et al., 1999; Heus et al., 2009).

Cloud samples are divided into three regimes based on f_{ad} : sub-adiabatic ($0.5 < f_{ad} < 1.0$), strongly diluted ($0.1 < f_{ad} < 0.5$), and very strongly diluted ($0 < f_{ad} < 0.1$) cloud samples. r_e profiles in the three f_{ad} regimes are shown in Fig. 7. r_e in sub-adiabatic cloud samples ($0.5 < f_{ad} < 1.0$) are generally larger than the median r_e of all cloud samples (Fig. 7a–4c), while r_e in very strongly diluted cloud samples ($0 < f_{ad} < 0.1$) are generally smaller than the median r_e of all cloud samples (Figs. 7g–4i). r_e generally becomes smaller as f_{ad} decreases, showing that smaller r_e is caused by more entrainment mixing, especially for the non-precipitating polluted and intermediate cases. The degree of r_e variability is also highly correlated with the degree of mixing. Note that most cloud samples are strongly diluted ($0.1 < f_{ad} < 0.5$). However, it is in the very strongly diluted regime ($0 < f_{ad} < 0.1$) that r_e has the highest variability. r_e in the sub-adiabatic regime ($0.5 < f_{ad} < 1.0$) has small variability. For the clean, precipitating case, the strongly diluted and very strongly diluted cloud samples have drops that are much larger than the median r_e due to droplet collision-coalescence and sedimentation. We do not discuss mixing effects for the clean case as f_{ad} cannot be used as an approximation for the degree of mixing in this case.

3.4 Effect of vertical inhomogeneity on shortwave radiative forcing

The vertical profiles of LWC and r_e used in the SBDART model are shown in Fig. 8. Profiles for the vertically inhomogeneous clouds are based on the LES simulations. The LWC of the vertically homogeneous cloud is chosen in the way that the two clouds have the same LWP. We vary the r_e of the vertically homogeneous cloud until the two clouds have the same radiative forcing. The r_e of the vertically homogeneous cloud, along with the cloud-top r_e of the vertically inhomogeneous cloud (as in Fig. 8), are listed in Table 1. Shortwave radiative forcings both at the surface and at TOA are investigated. It is seen that the r_e of the vertically homogeneous cloud must be about

76–90% of the vertically inhomogeneous cloud in order for them to have the same shortwave radiative forcing. The smaller values (~76%) are associated with clean clouds that exhibit large vertical variation in r_e while the larger values (~90%) are for polluted clouds with small vertical variation in r_e . Results in this study are consistent
5 with previous findings on stratified clouds (Brenguier et al., 2003).

4 Conclusions

Analyses of r_e profiles in shallow convective clouds simulated with LES show that in-cloud r_e increases with height for polluted ($N_a=2000 \text{ mg}^{-1}$) and intermediate ($N_a=100 \text{ mg}^{-1}$) aerosol conditions. Under clean conditions ($N_a=25 \text{ mg}^{-1}$), the in-cloud

10 r_e has high variability at each level. Cloud-top r_e of a population of clouds, each at a different stage of development, were used to construct a profile of r_e . It is seen that, on average, the constructed r_e is in agreement with the in-cloud r_e at the same height for the polluted and intermediate cases, but with a low bias (about 10%). This suggests that the cloud-top r_e measured from satellites can be used to represent the in-cloud r_e
15 at the same height with a low bias for cumulus clouds that have negligible precipitation. (This bias is alleviated if profiles are constructed using r_e at one grid below the cloud top.) However, for the clean case where drizzle develops, r_e profiles are complicated due to droplet collision-coalescence and sedimentation, and hence more difficult to characterize. The constructed r_e profiles in this case cannot be used to represent
20 the in-cloud r_e profiles because both the in-cloud r_e and the constructed r_e are highly variable. Here in the LES simulation, we assume entrainment mixing is homogeneous, and conclude that cloud-top r_e can represent the in-cloud r_e with a low bias (10%) for cumulus clouds that have negligible precipitation. If mixing is inhomogeneous, the constructed r_e profile should be closer to the in-cloud r_e profile.

25 In general, this study shows that the ability to distinguish a cloud under a clean aerosol condition from that under a polluted aerosol condition using both the in-cloud r_e and the constructed r_e is good, provided the range of aerosol concentration is high and

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that the satellite retrieval of r_e is robust. But for relatively small aerosol concentration gradients, the variability of r_e will make it difficult to do so.

Investigation of r_e evolution for individual clouds and the cloud population indicates that r_e becomes smaller (about 10%) as the cloud develops into the decaying stage.

- 5 The subadiabatic characteristics of the simulated cases are investigated. The adiabatic fraction f_{ad} is significantly less than 1 at all heights for the three cases, with the cloud top having smaller f_{ad} , due to stronger entrainment mixing. In addition, f_{ad} becomes smaller as clouds develop into the decaying stage. The stronger mixing at cloud top and in the decaying stage of the clouds can lead to smaller r_e . This is the reason why
- 10 the constructed r_e profiles have a low bias compared to the in-cloud r_e , and decaying clouds have smaller r_e than the growing clouds. Results in this paper show that r_e becomes progressively smaller and the variability of r_e also becomes progressively larger as f_{ad} decreases in the polluted and intermediate cases. However, for the clean, precipitating case, f_{ad} cannot be used to represent the degree of mixing, because both
- 15 entrainment mixing and sedimentation affect the distribution of liquid water.

For a vertically homogeneous cloud and a vertically inhomogeneous cloud with the same LWP, r_e of the vertically homogeneous cloud must be about 76–90% of the cloud-top r_e of the vertically inhomogeneous cloud in order to have the same shortwave radiative forcing. This result for cumulus clouds is consistent with previous studies on

20 stratiform clouds, and indicates that the estimation of cloud shortwave radiative forcing using measured cloud-top r_e needs to be treated carefully.

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	$N_a = 2000 \text{ mg}^{-1}$	$N_a = 100 \text{ mg}^{-1}$	$N_a = 25 \text{ mg}^{-1}$
r_e (μm) of the highest sublayer in the vertically inhomogeneous cloud (as in Fig. 8)	4.8	13.0	22.9
r_e (μm) of the vertically homogeneous cloud when two clouds have the same radiative forcing at the surface	4.2 (87.5%)	10.8 (83.1%)	17.5 (76.4%)
r_e (μm) of the vertically homogeneous cloud when two clouds have the same radiative forcing at TOA	4.3 (89.6%)	11.0 (84.6%)	18.0 (78.6%)

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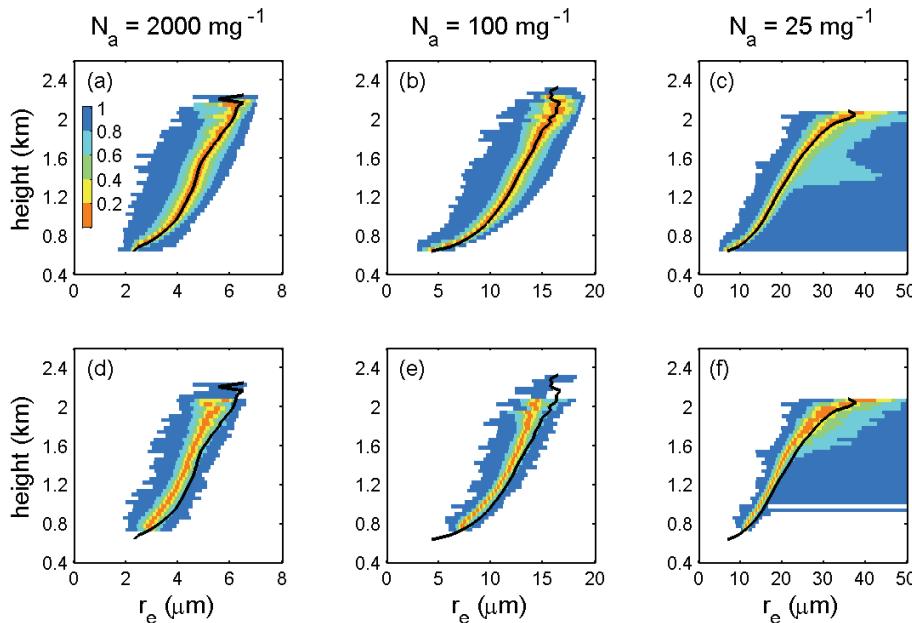


Fig. 1. r_e profiles of cloud population in the last 4 h of simulation in the polluted ($N_a=2000 \text{ mg}^{-1}$), intermediate ($N_a=100 \text{ mg}^{-1}$), and clean ($N_a=25 \text{ mg}^{-1}$) cases. **(a–c)** r_e profiles from all cloud samples. **(d–f)** Constructed r_e profiles using cloud-top r_e . Different colors represent different percentiles. (Orange: 40–60 percentiles; yellow: 30–40, 60–70 percentiles; green: 20–30, 70–80 percentiles; cyan: 10–20, 80–90 percentiles; blue: 0–10, 90–100 percentiles.) Notice that data points are few near cloud top so that only blue is used to represent 0–100 percentiles. The drizzle mode drops (larger than 50 μm) in clouds and below cloud base are not shown in the clean case for clarity. The 50th percentile of the r_e from all cloud samples in each case are shown for reference (black lines).

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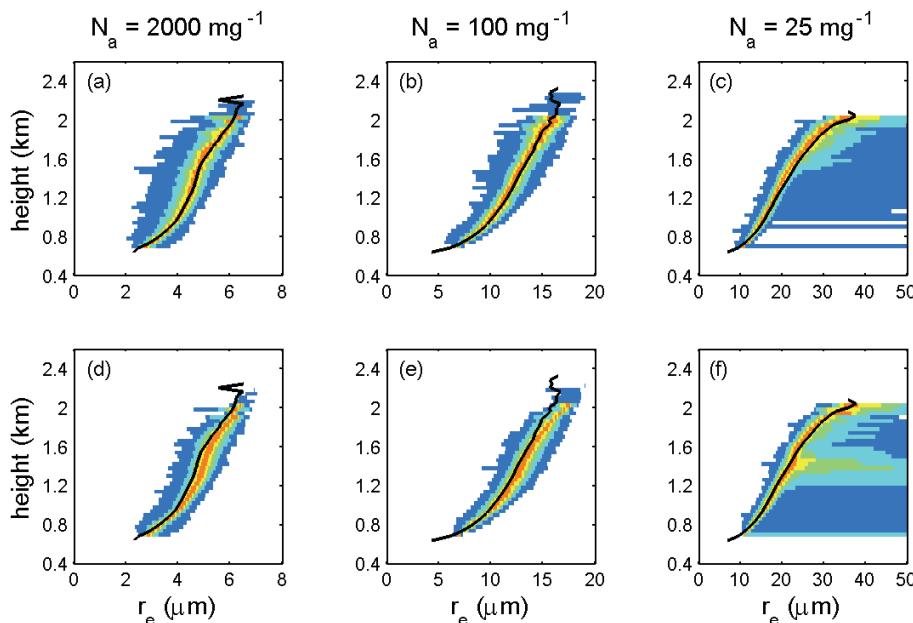


Fig. 2. Constructed r_e profiles using different measures of cloud-top r_e . **(a–c)** Using r_e at one grid point below the highest grid that has $q_l > 0.01 \text{ g kg}^{-1}$. **(d–f)** Using maximum r_e in the column. Color scale is the same as Fig. 1. The 50th percentile of the r_e from all cloud samples in each case are shown for reference (black lines, same as Fig. 1).

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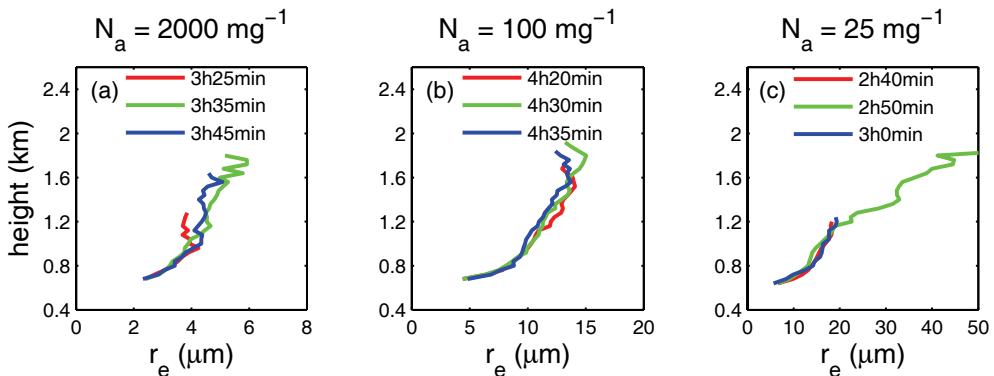


Fig. 3. Evolution of r_e profiles of individual clouds throughout their lifetime in each case. **(a)** A cloud in the polluted case evolving from 3 h 15 min to 3 h 55 min. The cloud reaches the maximum height at 3 h 35 min. **(b)** A cloud in the intermediate case from 4 h 10 min to 4 h 35 min, reaching the maximum height at 4 h 30 min. **(c)** A cloud in the clean case from 2 h 30 min to 3 h 5 min. It reaches the maximum height at 2 h 50 min. Only the r_e profile at the time with the maximum height, and two profiles before and after the maximum height are shown.

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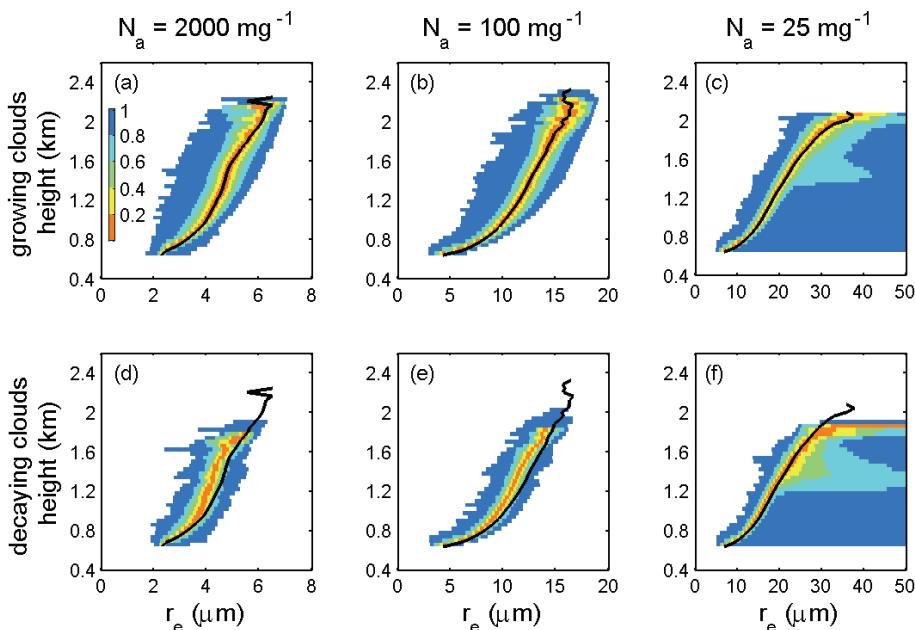


Fig. 4. r_e profiles from different cloud samples in the last 4 h of simulation for the three cases. (**a–c**) growing clouds, maximum $w>2.0\text{ m s}^{-1}$; (**d–f**) decaying clouds, maximum $w<2.0\text{ m s}^{-1}$. Black lines are the 50th percentiles of the r_e from all cloud samples for reference (same as in Fig. 1). Color scale is the same as Fig. 1.

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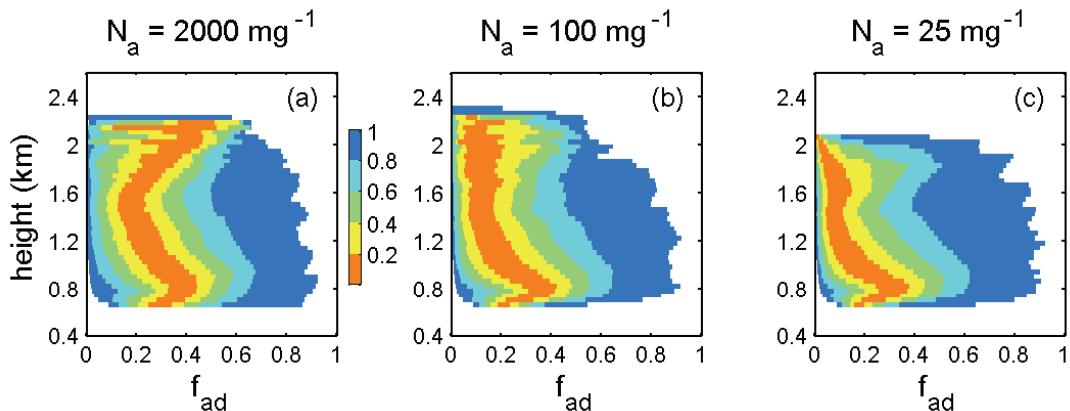


Fig. 5. Averaged profiles of adiabatic fraction (f_{ad}) over the last 4 h of simulation for the three cases. Color scale is the same as Fig. 1.

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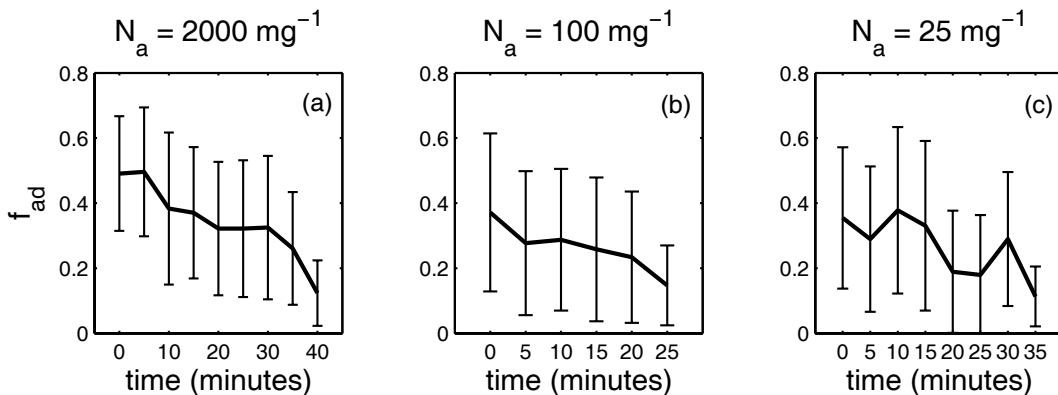


Fig. 6. Evolution of f_{ad} for the individual clouds shown in Fig. 3.

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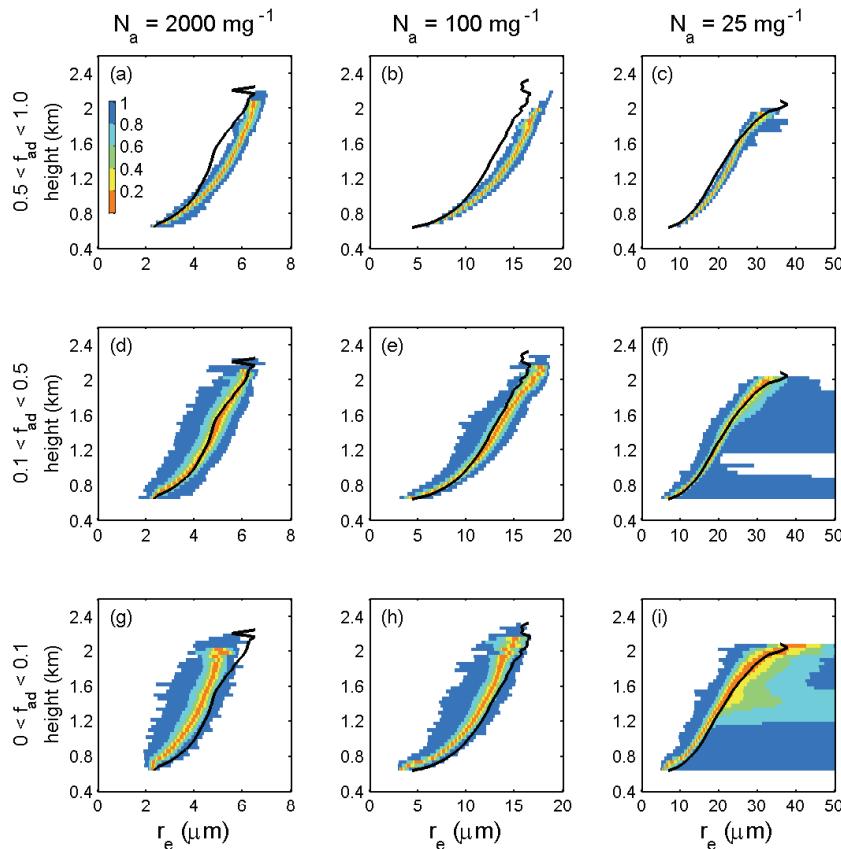


Fig. 7. r_e profiles from different cloud samples over the last 4 h of simulation for the three cases. (a–c) sub-adiabatic regime ($0.5 < f_{\text{ad}} < 1.0$); (d–f) strongly diluted regime ($0.1 < f_{\text{ad}} < 0.5$); (g–i) very strongly diluted regime ($0 < f_{\text{ad}} < 0.1$). Black lines are the 50th percentiles of the r_e from all cloud samples for reference (same as in Fig. 1). Color scale is the same as Fig. 1.

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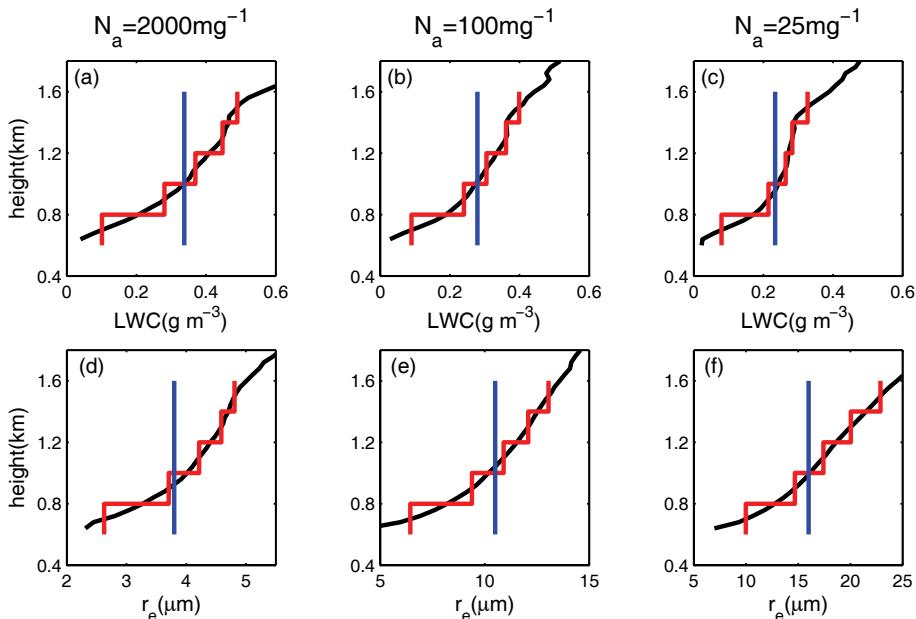


Fig. 8. (a–c) Idealized LWC profiles and **(d–f)** idealized r_e profiles for the input of the SBDART model. Black lines: LES model results. Red lines: Vertically inhomogeneous clouds that have 5 sublayers covering the height range $z=600\text{--}1600\text{ m}$; profiles are based on LES simulations. Blue lines: Vertically homogeneous clouds (the r_e shown here is one of the values used in the SBDART model for each case). Note that the two clouds have the same LWP. We vary the r_e of the vertically homogeneous cloud until it has the same radiative forcing as the vertically inhomogeneous cloud.

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